

YK600XG

Standard type: Medium type

- Arm length 600mm
- Maximum payload 10kg



Ordering method

YK600XG

Model	Z axis stroke	Tool flange	Cable
	200: 200mm 300: 300mm	No entry: None F: With tool flange	3L: 3.5m 5L: 5m 10L: 10m

RCX340-4

Controller / Number of controllable axes	Safety standard	Option A (OP.A)	Option B (OP.B)	Option C (OP.C)	Option D (OP.D)	Option E (OP.E)	Absolute battery
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Specify various controller setting items. RCX340 ▶ P.508

RCX240

Controller	CE Marking	Regenerative unit	Expansion I/O	Network option	IVY System	Gripper	Battery
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Specify various controller setting items. RCX240/RCX240S ▶ P.495

Specifications

		X-axis	Y-axis	Z-axis	R-axis
Axis specifications	Arm length	300 mm	300 mm	200 mm	300 mm
	Rotation angle	+/-130 °	+/-145 °	-	+/-360 °
AC servo motor output		400 W	200 W	200 W	200 W
Deceleration mechanism	Speed reducer	Harmonic drive	Harmonic drive	Ball screw	Harmonic drive
	Transmission method	Direct-coupled			
	Motor to speed reducer	Direct-coupled			
	Speed reducer to output	Direct-coupled			
Repeatability ^{Note 1}		+/-0.01 mm		+/-0.01 mm	+/-0.004 °
Maximum speed		8.4 m/sec		2.3 m/sec 1.7 m/sec	1700 °/sec
Maximum payload		10 kg			
Standard cycle time: with 2kg payload ^{Note 2}		0.46 sec			
R-axis tolerable moment of inertia ^{Note 3}		0.30 kgm ²			
User wiring		0.2 sq × 20 wires			
User tubing (Outer diameter)		φ 6 × 3			
Travel limit		1.Soft limit 2.Mechanical stopper (X,Y,Z axis)			
Robot cable length		Standard: 3.5 m Option: 5 m, 10 m			
Weight		31 kg			

Note 1. This is the value at a constant ambient temperature. (X,Y axes)
 Note 2. When reciprocating 300mm in horizontal and 25mm in vertical directions.
 Note 3. There are limits to acceleration coefficient settings. See P.539.

Controller

Controller	Power capacity (VA)	Operation method
RCX340 RCX240-R3	1700	Programming / I/O point trace / Remote command / Operation using RS-232C communication

Note. "Harmonic" and "Harmonic drive" are the registered trademarks of Harmonic Drive Systems Inc.

Note. The movement range can be limited by changing the positions of X and Y axis mechanical stoppers. (The movement range is set to the maximum at the time of shipment.)
 See our robot manuals (installation manuals) for detailed information.

Note. To set the standard coordinates with high accuracy, use a standard coordinate setting jig (option). Refer to the user's manual (installation manual) for more details.

Our robot manuals (installation manuals) can be downloaded from our website at the address below:
<http://global.yamaha-motor.com/business/robot/>

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