

T4L

Origin on the non-motor side is selectable

Controller: 24V



Ordering method

T4L							ERC	
Model	Lead designation	Brake	Origin position change	Grease type	Stroke	Cable length ^{Note 1}	Controller	I/O connector specification
	12: 12mm 6: 6mm 2: 2mm	No entry: No brakes BK: Brakes provided	None: Standard Z: Non-motor side	None: Standard GC: Clean	50 to 400 (50mm pitch)	1L: 1m 3L: 3.5m 5L: 5m 10L: 10m 1K/3K/5K/10K (Flexible cable)		CN1: I/O flat cable 1m (Standard) CN2: Twisted-pair cable 2m (pulse train function)

Note 1. The robot cable is standard cable (1L/3L/5L/10L), but can be changed to flexible cable. See P.594 for details on robot cable.

Specifications

AC servo motor output (W)	30		
Repeatability ^{Note 1} (mm)	+/-0.02		
Deceleration mechanism	Ball screw $\phi 8$ (Class C10)		
Ball screw lead (mm)	12	6	2
Maximum speed (mm/sec)	720	360	120
Maximum payload (kg)	Horizontal	4.5	
	Vertical	1.2	2.4
Rated thrust (N)		32	64
Stroke (mm)	50 to 400 (50mm pitch)		
Overall length (mm)	Horizontal	Stroke+198	
	Vertical	Stroke+236	
Maximum dimensions of cross section of main unit (mm)	W45 x H53		
Cable length (m)	Standard: 3.5 / Option: 1.5, 10		
Linear guide type	2 rows of gothic arch grooves x 1 rail		
Position detector	Resolvers ^{Note 2}		
Resolution (Pulse/rotation)	16384		

Note 1. Positioning repeatability in one direction.

Note 2. Position detectors (resolvers) are common to incremental and absolute specifications. If the controller has a backup function then it will be absolute specifications.

Allowable overhang^{Note}

Horizontal installation (Unit: mm)				Wall installation (Unit: mm)				Vertical installation (Unit: mm)				
Lead	Weight	A	B	Lead	Weight	A	B	Lead	Weight	C		
Lead 12	2kg	433	87	180	Lead 12	2kg	149	54	Lead 12	1.2kg	125	125
	4.5kg	223	33	75		4.5kg	50	1		148	2.4kg	56
Lead 6	3kg	515	58	135	Lead 6	3kg	107	24	Lead 6	3kg	41	42
	6kg	340	26	62		6kg	31	0		195	7.2kg	0
Lead 2	3kg	1585	58	142	Lead 2	3kg	113	24	Lead 2	3kg	41	42
	6kg	755	27	66		6kg	32	0		440	7.2kg	0

Note. Distance from center of slider top to center of gravity of object being carried at a guide service life of 10,000 km.

Note. Service life is calculated for 300mm stroke models.

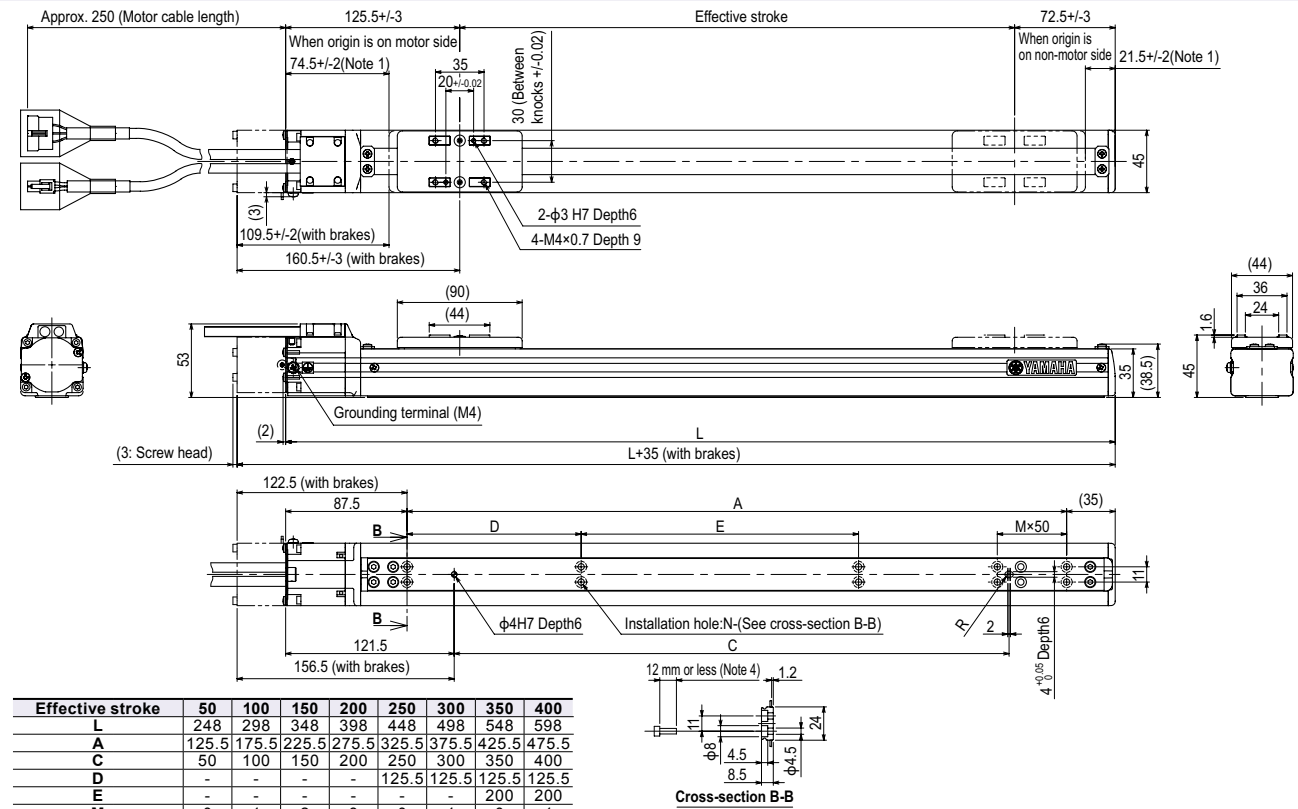
Static loading moment

(Unit: N·m)		
MY	MP	MR
15	19	18

Controller

Controller	Operation method
ERC	Pulse train control / Programming / I/O point trace / Remote command / Operation using RS-232C communication

T4L



Note 1. Stop positions are determined by the mechanical stoppers at both ends.

Note 2. Minimum bend radius of motor cable is R30.

Note 3. Weight of models with no brake. The weight of brake-attached models is 0.2 kg heavier than the models with no brake shown in the table.

Note 4. The under-head length of the hex socket-head bolt (M4x0.7) to be used for the installation work is 12mm or less.

Note 5. External view of T4LH is identical to T4L.