

YK600XGP

Dust-proof & drip-proof type

- Arm length 600mm
- Maximum payload 8kg

Ordering method

YK600XGP **F** **RCX340-4**

Model Z axis stroke Tool flange Cable

200: 200mm F: With tool flange 3L: 3.5m Controller / Number of controllable axes

300: 300mm 5L: 5m 10L: 10m Safety standard Option A (OP.A) Option B (OP.B) Option C (OP.C) Option D (OP.D) Option E (OP.E) Absolute battery

RCX240 **R3** **BB**

Controller CE Marking Regenerative unit Expansion I/O Network option iVY System Gripper Battery

Specify various controller setting items. RCX340 ▶ **P.508**

Specify various controller setting items. RCX240/RCX240S ▶ **P.495**

Specifications

| | | X-axis | Y-axis | Z-axis | R-axis |
|---|---|--|----------------|---------------|----------------|
| Axis specifications | Arm length | 300 mm | 300 mm | 200 mm 300 mm | — |
| | Rotation angle | +/-130 ° | +/-145 ° | — | +/-360 ° |
| AC servo motor output | | 400 W | 200 W | 200 W | 200 W |
| Deceleration mechanism | Speed reducer | Harmonic drive | Harmonic drive | Ball screw | Harmonic drive |
| | Transmission method | Direct-coupled | | | |
| | Motor to speed reducer Speed reducer to output | Direct-coupled | | | |
| Repeatability ^{Note 1} | | +/-0.01 mm | +/-0.01 mm | +/-0.01 mm | +/-0.004 ° |
| Maximum speed | | 8.4 m/sec | 2.3 m/sec | 1.7 m/sec | 1700 °/sec |
| Maximum payload | | 8 kg | | | |
| Standard cycle time: with 2kg payload ^{Note 2} | | 0.56 sec | | | |
| R-axis tolerable moment of inertia ^{Note 3} | | 0.3 kgm ² | | | |
| Protection class ^{Note 4} | | Equivalent to IP65 (IEC 60529) | | | |
| User wiring (sq × wires) | | 0.2 × 20 | | | |
| User tubing (Outer diameter) | | φ 6 × 3 | | | |
| Travel limit | | 1.Soft limit 2.Mechanical stopper (X,Y,Z axis) | | | |
| Robot cable length | | Standard: 3.5 m Option: 5 m, 10 m | | | |
| Weight | | Z axis 200 mm: 33 kg Z axis 300 mm: 34 kg | | | |

Note 1. This is the value at a constant ambient temperature. (X,Y axes)
 Note 2. When reciprocating 25mm in vertical direction and 300mm in horizontal direction (rough-positioning arch motion).
 Note 3. There are limits to acceleration coefficient settings. See P.539.
 Note 4. Do not use robots where the bellows section is directly exposed to water jet. Contact our distributor for information on drip-proof structure preventing liquid other than water.

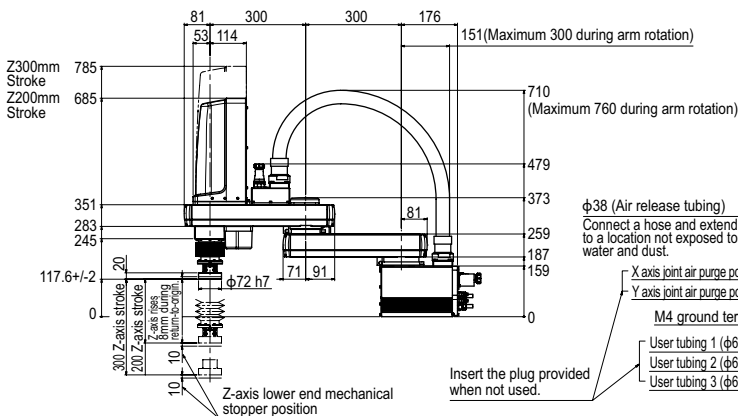
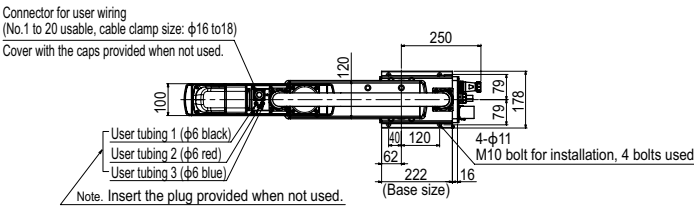
Controller

| Controller | Power capacity (VA) | Operation method |
|---------------------|---------------------|--|
| RCX340 RCX240-R3 | 1700 | Programming / I/O point trace / Remote command / Operation using RS-232C communication |

Note. "Harmonic" and "Harmonic drive" are the registered trademarks of Harmonic Drive Systems Inc.
 Note. The movement range can be limited by changing the positions of X and Y axis mechanical stoppers. (The movement range is set to the maximum at the time of shipment.)
 See our robot manuals (installation manuals) for detailed information.
 Note. To set the standard coordinates with high accuracy, use a standard coordinate setting jig (option). Refer to the user's manual (installation manual) for more details.

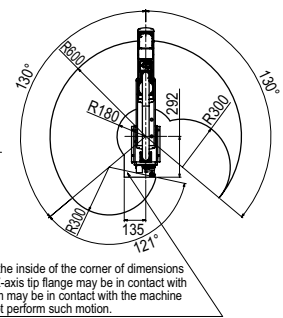
Our robot manuals (installation manuals) can be downloaded from our website at the address below:
<http://global.yamaha-motor.com/business/robot/>

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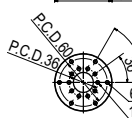
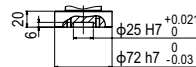
If the robot enters the inside of the corner of dimensions 135 and 292, the Z-axis tip flange may be in contact with the base or the arm may be in contact with the machine harness. So, do not perform such motion.

Working envelope of left-handed system



Working envelope of right-handed system

- Note that the robot cannot be used at a position where the base flange, robot cable, spline, and bellows interfere with each other in the working envelope shown above.
- X-axis mechanical stopper position : 132°
- Y-axis mechanical stopper position : 147°



* There is no phase relation between each position of M5 tapped holes and R-axis origin position.

Z axis tip shape