| Specifications |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  |  | X-axis | Y-axis | Z-axis | R -axis |
| Axis specifications | Arm length |  | 75 mm | 75 mm | 50 mm | - |
|  | Rotation angle |  | +/-125 ${ }^{\circ}$ | +/-145 ${ }^{\circ}$ | - | +/-360 ${ }^{\circ}$ |
| AC servo motor output |  |  | 30 W | 30 W | 30 W | 30 W |
| Deceleration mechanism | Speed reducer |  | Harmonic drive | Harmonic drive | Ball screw | Harmonic drive |
|  | Transmission method | Motor to speed reducer | Direct-coupled |  |  |  |
|  |  | Speed reducer to output | Direct-coupled |  |  |  |
| Repeatability ${ }^{\text {Note } 1}$ |  |  | +/-0.01 mm |  | +/-0.01 mm | +/-0.004 ${ }^{\circ}$ |
| Maximum speed |  |  | $3.4 \mathrm{~m} / \mathrm{sec}$ |  | $0.9 \mathrm{~m} / \mathrm{sec}$ | 1700 \%sec |
| Maximum payload |  |  | 1.0 kg |  |  |  |
| Standard cycle time: with 0.1kg payload ${ }^{\text {Note } 2}$ |  |  | 0.33 sec |  |  |  |
| R -axis tolerable moment of inertia ${ }^{\text {Note } 3}$ |  |  | $0.01 \mathrm{kgm}^{2}$ |  |  |  |
| User wiring |  |  | $0.1 \mathrm{sq} \times 8$ wires |  |  |  |
| User tubing (Outer diameter) |  |  | $\phi 4 \times 2$ |  |  |  |
| Travel limit |  |  | 1.Soft limit 2.Mechanical stopper ( $\mathrm{X}, \mathrm{Y}, \mathrm{Z}$ axis) |  |  |  |
| Robot cable length |  |  | Standard: 2 m Option: $3.5 \mathrm{~m}, 5 \mathrm{~m}, 10 \mathrm{~m}$ |  |  |  |
| Weight (Excluding robot cable) ${ }^{\text {Note } 4}$ |  |  | 4.0 kg |  |  |  |
| Robot cable weight |  |  | 0.9 kg (2 m) | $1.5 \mathrm{~kg}(3.5 \mathrm{~m})$ | 2.1 kg (5 m) | 2 kg (10 m) |


| Controller |  |  |
| :---: | :---: | :---: |
| Controller | Power capacity (VA) | Operation method |
| RCX340 | 300 | Programming / <br> I/O point trace / <br> Rexnote command / <br> Operation |
| using RS-232C |  |  |
| communication |  |  |

Note. "Harmonic" and "Harmonic drive" are the registered trademarks of Harmonic Drive Systems Inc.
Note. The movement range can be limited by changing the positions of $X$ and $Y$ axis mechanical stoppers. (The movement range is set to the maximum at the time of shipment.) See our robot manuals (installation manuals) for detailed
information. information

| Our robot manuals (installation manuals) can be <br> downloaded from our website at the address below: <br> http://global.yamaha-motor.com/business/robot/ |
| :--- |

Note 1. This is the value at a constant ambient temperature. ( $X, Y$ axes)
Note 2. When moving 25 mm in vertical direction and 100 mm in horizontal direction reciprocally.
Note 3. There are limits to acceleration coefficient settings. See P. 536 .
Note 4. The total robot weight is the sum of the robot body weight and the cable weight


