

Standard type: Tiny type

Arm length 180mm
Maximum payload 1kg

■ Ordering method

YK180XG - 50 RCX340-4 Cable 2L: 2m 3L: 3.5m 5L: 5m 10L: 10m Specify various controller setting items. RCX340 ▶ P.508 RCX240S BB

Specify various controller setting items. RCX240/RCX240S ▶ P.495

- CE Marking - Expansion I/O - Network option - iVY System - Gripper - Battery

■ Specifications							
			X-axis	Y-axis	Z-axis	R-axis	
Axis	Arm length		105 mm	75 mm	50 mm	-	
specifications	Rotation angle		+/-125 °	+/-145 °	-	+/-360 °	
AC servo motor output			30 W	30 W	30 W	30 W	
Deceleration mechanism	Speed reducer		Harmonic drive	Harmonic drive	Ball screw	Harmonic drive	
	Transmission method	Motor to speed reducer	Direct-coupled				
		Speed reducer to output	Direct-coupled				
Repeatability Note 1			+/-0.01 mm +/-0.01 mm +/-0.004		+/-0.004 °		
Maximum speed			3.3 m/sec 0.9 m/sec 1700 °/sec		1700 °/sec		
Maximum payload			1.0 kg				
Standard cycle time: with 0.1kg payload Note 2			0.33 sec				
R-axis tolerable moment of inertia Note 3			0.01 kgm ²				
User wiring			0.1 sq × 8 wires				
User tubing (C	Outer diameter)	ф 4 × 2				
Travel limit			1.Soft limit 2.Mechanical stopper (X,Y,Z axis)				
Robot cable length			Standard: 2 m Option: 3.5 m, 5 m, 10 m				
Weight (Excluding robot cable) Note 4			4.1 kg				
Robot cable weight			0.9 kg (2 m) 1.5 kg (3.5 m) 2.1 kg (5 m) 4.2 kg (10 m)				

■ Controller								
Controller	Power capacity (VA)	Operation method						
RCX340 RCX240S	500	Programming / I/O point trace / Remote command / Operation using RS-232C communication						

Note. "Harmonic" and "Harmonic drive" are the registered trademarks of Harmonic Drive Systems Inc.

Note. The movement range can be limited by changing the positions of X and Y axis mechanical stoppers. (The movement range is set to the maximum at the time of shipment.) See our robot manuals (installation manuals) for detailed information.

> Our robot manuals (installation manuals) can be downloaded from our website at the address below http://global.yamaha-motor.com/business/robot/

Note 1. This is the value at a constant ambient temperature. (X,Y axes)

Note 2. When moving 25mm in vertical direction and 100mm in horizontal direction reciprocally. Note 3. There are limits to acceleration coefficient settings. See P.536. Note 4. The total robot weight is the sum of the robot body weight and the cable weight.

