

YAMAHA
ROBOT



Estratto Catalogo Yamaha
Assi con motori lineari (Serie Phaser)

PHASER Series

Product Lineup

LINEAR MOTOR SINGLE-AXIS ROBOTS

No limit on critical speed even when using a long stroke of 4 m.
"PHASER" series delivers superb performance
during long distance transfer.



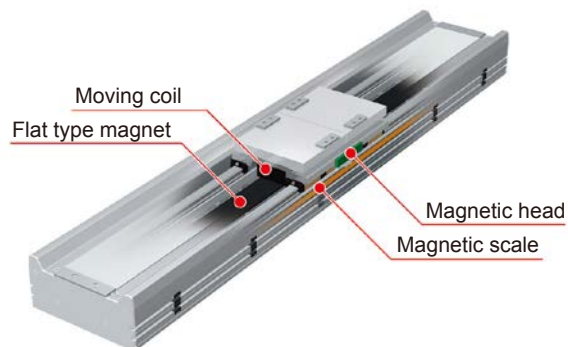
Critical speed is not restricted and high-speed long-stroke transfer is possible.

MF type

High-power and long-stroke using flat motor with core

P.218

- Maximum stroke: 4050 mm
- Maximum speed: 2500 mm/s
- Repeated positioning accuracy: +/-5 μm
- Maximum payload: 7 to 160 kg

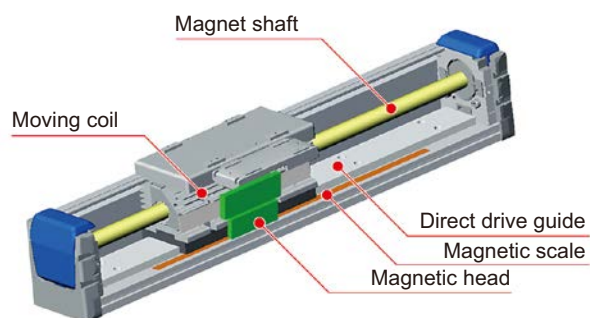
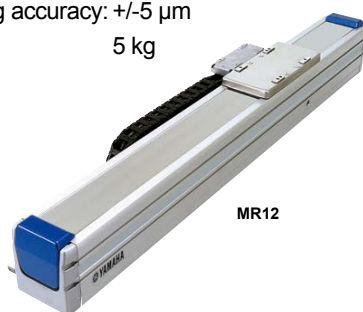


MR type

Lightweight, compact, and low cogging by shaft motor drive

P.236

- Maximum stroke: 1050 mm
- Maximum speed: 2500 mm/s
- Repeated positioning accuracy: +/-5 μm
- Maximum payload: 5 kg



Type	Size (mm) ^{Note 1}	Model	Carrier	Maximum payload (kg)	Maximum speed (mm/sec.)	Stroke (mm)	Page
MF type Flat type with core Linear motor specifications	W85 × H80	MF7	Single	10 (7) ^{Note 2}	2500	100 to 4000	P.218
		MF7D	Double			100 to 3800	
	W100 × H80	MF15	Single	30 (15) ^{Note 2}		100 to 4000	P.224
		MF15D	Double			100 to 3800	
	W150 × H80	MF20	Single	40 (20) ^{Note 2}		150 to 4050	P.228
		MF20D	Double			150 to 3850	
		MF30	Single	60 (30) ^{Note 2}		100 to 4000	
		MF30D	Double			150 to 3750	
W210 × H100	MF75	Single	160 (75) ^{Note 2}	1000 to 4000	P.234		
	MF75D	Double		680 to 3680			
MR type Shaft type Linear motor specifications	W60 × H90	MR12	Single	5	50 to 1050	P.236	
		MR12D	Double		50 to 1050		

Note 1. The size shows approximate maximum cross sectional size.

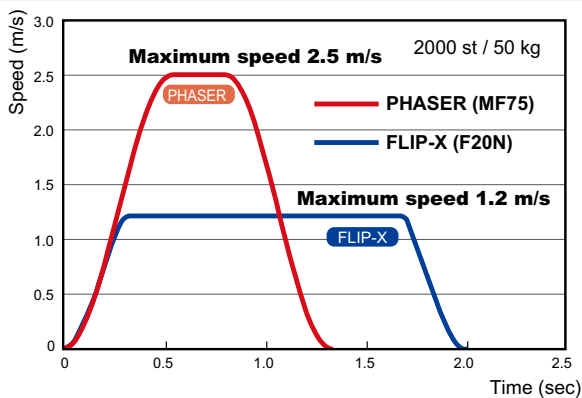
Note 2. When using at the maximum speed, the maximum payload becomes the value in ().

POINT 1

Maximum speed 2.5 m/sec. and no critical speed limit

The ultimate appeal of the linear motor single-axis robot is that there are no restrictions on critical speed like ball screw. The maximum speed does not decrease even with long-distance transfer. Additionally, the maximum stroke of the MR type is set to up to 1050 mm and that of the MF type is set to up to 4000 mm with standard settings. In particular, the cycle time of the long-distance transfer is greatly improved.

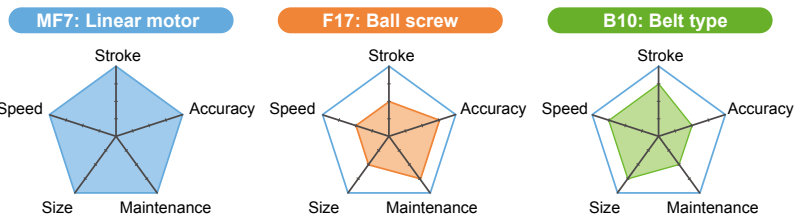
Movement time comparison between linear single-axis robot PHASER and single-axis robot FLIP-X



POINT 4

In-house manufacturing of major parts achieves low costs.

Magnetic scales are developed and manufactured at YAMAHA. In-house manufacturing of other major parts achieves large cost reduction. Nowadays, the linear motor is not a special mechanism. The customer can select the linear motor or ball screw in the similar way according to the customer's needs. In particular, when performing a high-speed and long-distance transfer of a light workpiece, selecting linear motor robots may reduce the cost.



Comparison of single-axis robot models

Model name	Main body price ^{Note 1}	Maximum speed (mm/sec.)	Maximum payload (kg)	Repeated positioning accuracy (μm)	Maximum stroke (mm)	Maximum cross-sectional dimension ^{Note 2} (mm)
MF7-1500		2500	10 (7) ^{Note 3}	+/- 5	4000	W85 × H80
F17-40-1450		720 ^{Note 4}	40	+/- 10	1450	W168 × H100
B10-1450		1850	10	+/- 40	2550	W100 × H81

Note 1: The prices are compared with the strokes shown above.
 Note 2: Cable carriers are not included.
 Note 3: The payload is 7 kg when the maximum speed is 2500 mm/s. (10 kg-payload: 2100 mm/s)
 Note 4: This value is obtained by considering the critical speed with a stroke of 1450 mm.

POINT 5

Double-carrier available as standard

Double-carrier specifications that operate two carriers on one robot are available as standard. High effects, such as space saving, cost reduction, and tact improvement are obtained when compared to two single-axis robots. Furthermore, no axis alignment is needed and tools are commonly used to shorten the setup time. (When using the RCX series controller, an anti-collision function can be used.)

POINT 2

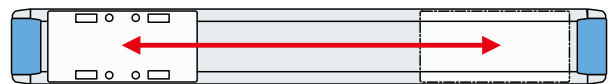
Suitable for heavy object transfer. Maximum payload 160 kg

The maximum payload of the MF type using a flat magnet is 160 kg. The robot can transfer a heavy object, such as large LCD panel at a high speed with high accuracy. (In the payload range of some MF types, the maximum speed may be restricted. For details, refer to the specification page of each model.)

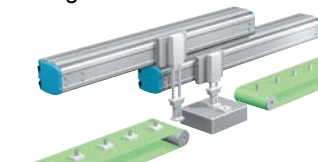
POINT 3

Effective use of stroke

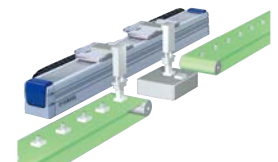
As the linear motor single-axis robot incorporates a coil that is the drive part inside the table, dead spaces are eliminated to maximize the stroke. Additionally, as the main body is symmetrical, the flexibility of the layout is improved.



Layout using two ball screw single-axis robots



Space saving using double-carrier



POINT 6

Linear scale developed by YAMAHA

YAMAHA originally developed a new linear scale based on its excellent magnetic signal detection technology.



Magnetic scale provides high environment resistance.

YAMAHA's magnetic scale is resistant to dirt and can be used in an environment where grease or cutting fluid sometimes splashes.

Semi-absolute specifications

The current position is obtained by reading the signal recorded in the linear scale. So, it is not necessary to perform a large return-to-origin movement before starting the operation after turning on the power (the slider moves up to 76 mm when reading the signals).

Cost reduction

In-house linear scale development and manufacturing achieves large cost reduction.

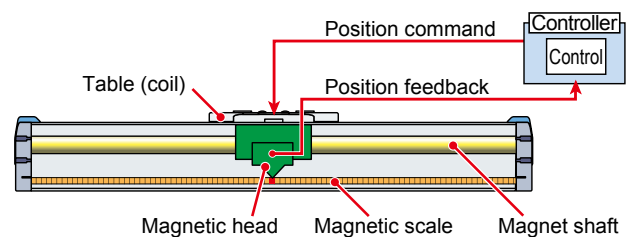
High resolution 1 μm

Magnetic signals recorded in the magnetic scale are detected and interpolated to achieve a highly accurate resolution of 1 μm .

Repeated positioning accuracy: $\pm 5 \mu\text{m}$

A fully-closed control that always feeds back the table position provides high accuracy steadily.

Additionally, there are no mechanical backlashes, such as ball screws or timing belts.



POINT 7

Silence and long service life

Unlike ball screw type robots, there are few sliding and rotating parts. So, the operation is very quiet. Moreover, as the coil is not in contact with the magnet, they are not worn out and can be used for an extended period of time.

POINT 8

Dust-proof structure

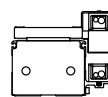
All YAMAHA's linear motor robots use a stainless steel shutter. This prevents entry of foreign objects. Additionally, these shutters are made of tough stainless steel with an extremely high fatigue strength to support high-speed and long-stroke operation.

POINT 9

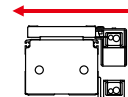
Flat type without cable carrier protrusion

For the MF7, as the main body is made compact, a flat type that the cable carrier becomes flat on the top surface of the table is prepared as standard. Please select this type according to the tool or workpiece shape, or installation method.

Standard type



Flat type



As the cable carrier does not protrude from the table upper surface in the flat type, a large tool can be installed easily.



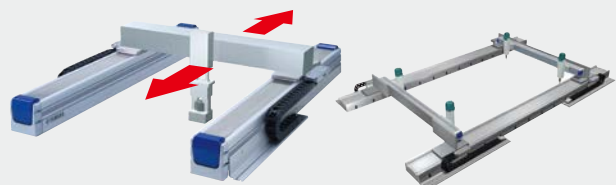
Applicable to multi-carrier operation

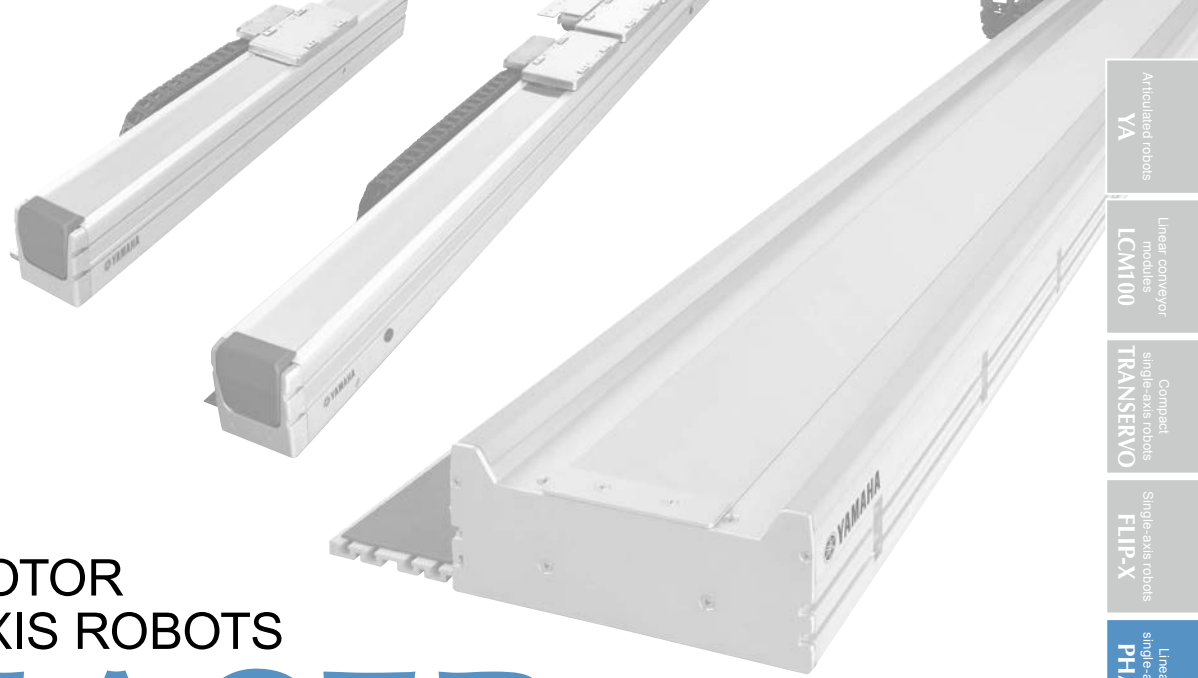
The PHASER series also supports "multi-carrier" operation that allows using three or more carriers on one robot. This "multi-carrier" operation drastically extends applications due to its high effect in improving tact time and saving space.



Applicable to dual-drive

As a dual-drive that simultaneously drives two axes, high-speed transfer and heavy object transfer are possible in a wide area. YAMAHA can propose an optimal control method according to the robot linkage rigidity.





LINEAR MOTOR SINGLE-AXIS ROBOTS

PHASER SERIES

Articulated robots YA
Linear conveyor modules LCM100
Compact single-axis robots TRANSERVO
Single-axis robots FLIP-X
Linear motor single-axis robots PHASER
Cartesian robots XY-X
SCARA robots YK-X
Pick & place robots YP-X
CLEAN
CONTROLLER
INFORMATION
MF type
MR type

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MR TYPE	
MR12/MR12D	236

PHASER SPECIFICATION SHEET

Type	Size (mm) ^{Note 1}	Model	Carrier	Maximum payload (kg)	Maximum speed (mm/sec.)	Stroke (mm)	Detailed info page
MF type Flat type with core Linear motor specifications	W85 × H80	MF7	Single	10 (7) ^{Note 2}	2500	100 to 4000 (Horizontal) 100 to 2000 (Wall mount)	P.218
		MF7D	Double			100 to 3800 (Horizontal) 100 to 1800 (Wall mount)	P.218
	W100 × H80	MF15	Single	30 (15) ^{Note 2}		100 to 4000 (Horizontal) 100 to 2000 (Wall mount)	P.224
		MF15D	Double			100 to 3800 (Horizontal) 100 to 1800 (Wall mount)	P.224
	W150 × H80	MF20	Single	40 (20) ^{Note 2}		150 to 4050	P.228
		MF20D	Double			150 to 3850	P.228
		MF30	Single	60 (30) ^{Note 2}		100 to 4000	P.231
		MF30D	Double			150 to 3750	P.231
	W210 × H100	MF75	Single	160 (75) ^{Note 2}		1000 to 4000	P.234
		MF75D	Double			680 to 3680	P.234
MR type Shaft type Linear motor specifications	W60 × H90	MR12	Single	5	50 to 1050	P.236	
		MR12D	Double		50 to 1050	P.236	

Note 1. The size shows approximate maximum cross sectional size.

Note 2. When using at the maximum speed, the maximum payload becomes the value in ().

⚠ Precautions for use

■ Handling

- Please be sure to read "PHASER Series Instruction Manual" carefully to have full understanding of its contents before using this product and strictly observe each instruction.
- Dropping or hitting this product may cause it to break. Always handle it carefully.
- Never disassemble this product. Entry of a foreign object will cause deterioration of accuracy.
- This product uses a magnetic type linear scale. Do not bring anything that generates a strong magnetic field near the robot itself as it may cause damage to the linear scale.

■ Installation place and environment

When installing this product, avoid the place where any of the following conditions applies.

- The ambient temperature is outside of the 0 °C to 40 °C range.
- Dielectric powder such as iron powder, dust, moist, salt or organic solvent is produced and flies in the air.
- Strong electric field, strong magnetic field, etc. occur.
- The product is affected by vibration or impact.
- Dewing occurs, or corrosive gas or combustible gas is generated.
- The product is exposed to direct sun or radiant heat.
- A noise source exists in the surrounding area.
- Inspection and cleaning cannot be performed.

■ Safety precaution

- A high performance rare earth magnets are used in the motor section of this product. For this reason, bringing a magnetic response type device or a medical device such as a heart pace maker close to the robot may cause it to malfunction. Be careful not to bring such a device close to the robot.

Robot ordering method description

In the order format for the YAMAHA linear motor single-axis robots PHASER series, the notation (letters/numbers) for the mechanical section is shown linked to the controller section notation.

[Example]

● Mechanical ▶ MF20

- Cable carrier take out direction ▷ RH
- Grease ▷ Standard
- Optional cable carrier for users ▷ S
- Stroke ▷ 550mm
- Origin position ▷ Change (R side)
- Cable length ▷ 3.5m

● Controller ▶ SR1-P

- Regenerative unit ▷ Required
- I/O selection ▷ NPN

● Ordering method

MF20 - RH - S - Z - 550 - 3L - SR1 - P10 - R - N

Mechanical section

Controller section

This page describes using the ordering form for mechanical components.

To find detailed controller information see the controller page.

SR1-P ▶ [P.516](#), TS-P ▶ [P.490](#), RDV-P ▶ [P.504](#)

Mechanical section

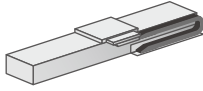
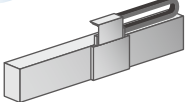
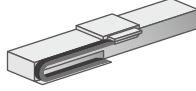
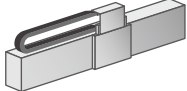
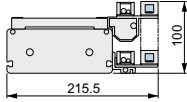
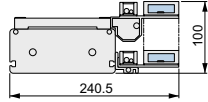
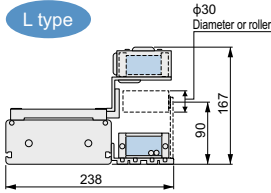
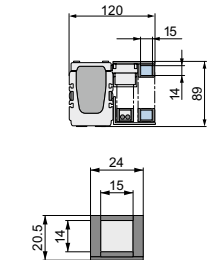
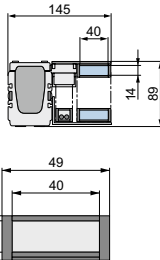
● Single carriage

① Model		② Cable carrier entry location	④ Optional cable carrier for users		⑤ Origin position change	⑥ Grease type		⑦ Stroke		⑧ Cable length	
MF7	MF7A	RH Horizontal, right	No entry	None	No entry	L side	No entry	Standard	3L	3.5m	
MF15	MF15A	LH Horizontal, left	S	S type	Z	R side	GC	Clean	5L	5m	
MF20	MF20A	RW Wall mounted, right	M	M type					10L	10m	
MF30	MF30A	LW Wall mounted, left	L	L type					3K	3.5m	
MF75	MF75A								5K	5m	
									10K	10m	

● Double carriage

① Model		③ Installing direction	④ Optional cable carrier for users		⑥ Grease type		⑦ Stroke		⑧ Cable length	
MF7D	MF7AD	H Horizontal installation	No entry	None	No entry	Standard	3L	3.5m		
MF15D	MF15AD		S	S type	GC	Clean	5L	5m		
MF20D	MF20AD	W Wall mounted installation	M	M type			10L	10m		
MF30D	MF30AD		L	L type			3K	3.5m		
MF75D	MF75AD						5K	5m		
							10K	10m		

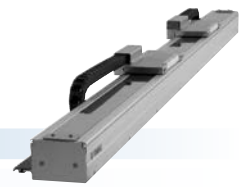
Robot ordering method terminology

<p>① Model</p>	<p>Enter the robot unit model. Select from 2 types: incremental specifications and semi-absolute specifications.</p>
<p>② Cable carrier entry location</p>	<p>Select what direction to install the robot (horizontal / wall mounted) and what direction to extract the robot cable carrier.</p> <div style="display: flex; justify-content: space-around; align-items: flex-start;"> <div style="text-align: center;"> <p>RH Horizontal, right</p>  </div> <div style="text-align: center;"> <p>RW Wall hanging, right</p>  </div> <div style="text-align: center;"> <p>LH Horizontal, left</p>  </div> <div style="text-align: center;"> <p>LW Wall hanging, left</p>  </div> </div> <p>Note. Be sure to install in the direction as specified (in cable carrier take-out direction drawing and various specification drawings) individually. Installation in any other way will cause a failure. For requirement of installation in any way other than the above standard installation, please consult YAMAHA as special arrangement will be available.</p>
<p>③ Installing direction</p>	<p>Select what direction to install the robot (horizontal / wall mounted).</p> <p>Please specify if a cable carrier is needed for customer wiring. [MF type] (For MF20)</p> <div style="display: flex; justify-content: space-around;"> <div style="text-align: center;"> <p>S type</p>  </div> <div style="text-align: center;"> <p>M type</p>  </div> <div style="text-align: center;"> <p>L type</p>  </div> </div> <p>Cable and pipe guide S : $\phi 8$ flexible cable x 1, $\phi 4$ air tube x 1 M : $\phi 8$ flexible cable x 2, $\phi 6$ air tube x 2 L : $\phi 8$ flexible cable x 2, $\phi 8$ air tube x 3</p> <p style="text-align: right;"> Space for optional cable for users</p> <p>[MR type]</p> <div style="display: flex; justify-content: space-around;"> <div style="text-align: center;"> <p>S type</p>  </div> <div style="text-align: center;"> <p>M type</p>  </div> </div> <p style="text-align: right;"> Space for optional cable for users</p> <p>Note. The cable and air hoses should take up less than 30% of the space when storing them inside the cable carrier. Lay out the cables and air hoses in rows inside the cable carrier so they do not cross each other.</p>
<p>⑤ Origin position change</p>	<p>Origin point position can be changed.</p>
<p>⑥ Grease type</p>	<p>Clean grease can be selected.</p>
<p>⑦ Stroke</p>	<p>Select the stroke for the robot operating range.</p>
<p>⑧ Cable length</p>	<p>Select the length of the robot cable connecting the robot to the controller.</p> <p>3L : 3.5m (Standard) 5L : 5m 10L : 10m 3K : 3.5m (Flexible cable) 5K : 5m (Flexible cable) 10K : 10m (Flexible cable)</p>

- Articulated robots
YA
- Linear conveyor modules
LCM100
- Compact single-axis robots
TRANSEVO
- Single-axis robots
FLP-X
- Linear motor single-axis robots
PHASER
- Cartesian robots
XY-X
- SCARA robots
YK-X
- Pick & place robots
YP-X
- CLEAN
- CONTROLLER INFORMATION
- MF type
- MR type

MF7/MF7D

- Flat type available
- Can be used for wall-mount



Ordering method

Single carriage model

MF7

Model MF7: Incremental MF7A: Semi-absolute ^{Note 1}	Cable carrier entry location RH: Horizontal, right LH: Horizontal, left FRH: Horizontal, right (Flat) FLH: Horizontal, left (Flat) RW: Wall mount, right LW: Wall mount, left	Optional cable carrier for users^{Note 2} No entry: None S: S type M: M type L: L type	Origin position change No entry: L side (Standard) Z: R side No entry: R side (Standard) Z: L side	Grease type No entry: Standard GC: Clean	Stroke^{Note 3} Horizontal (100mm pitch) 100 to 4000 5L: 5m 10L: 10m 3K/5K/10K (Flexible cable) ^{Note 5}	Cable length^{Note 4} 3L: 3.5m 5L: 5m 10L: 10m 3K/5K/10K (Flexible cable) ^{Note 5}
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TSP

Positioner^{Note 6} TS-P	Driver: Power-supply voltage / Power capacity 110: 100V/200W 210: 200V/200W	LCD monitor No entry: None L: With LCD	I/O selection NP: NPN PN: PNP CC: CC-Link DN: DeviceNet™ EP: EtherNet/IP™ GW: No I/O board ^{Note 7}
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SR1-P **10**

Controller	Driver: Power capacity 10: 200W	Usable for CE No entry: Standard E: CE marking	I/O selection N: NPN P: PNP CC: CC-Link DN: DeviceNet™ PB: PROFIBUS
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RDV-P **2** **10** **RBR1**

Driver	Power-supply voltage 2: AC200V	Driver: Power capacity 10: 200W or less	Regenerative unit
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Note 1. For the details of the semi-absolute model, please refer to P.33. RDV-P has an incremental model only.
 Note 2. For models with a 2,100mm or longer stroke, optional L type cable carriers can only be used. Flat type cannot be selected for L type.
 Note 3. Maximum stroke for flat type is 2000mm.
 Note 4. The robot cable is standard cable (3L/5L/10L), but can be changed to flexible cable. See P.594 for details on robot cable.
 Note 5. If a flexible cable is needed for the SR1-P, TS-P, or RDV-P, then select 3K/5K/10K. On the RCX221, the standard cable is a flexible cable, so enter 3L/5L/10L when ordering.
 Note 6. These controllers can be mounted on DIN rails. See P.498 for details.
 Note 7. Select this selection when using the gateway function. For details, see P.60.
 Note. It is possible to provide the model without a cable carrier. To find information on wiring (cable terminals) within the cable carrier see P.602.

Double carriage model

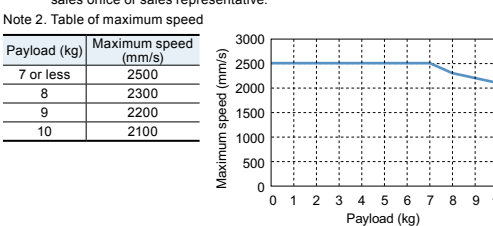
MF7D

Model MF7D: Incremental MF7AD: Semi-absolute ^{Note 1}	Installing direction H: Horizontal installation FH: Horizontal installation (Flat) W: Wall mount installation	Optional cable carrier for users^{Note 2} No entry: None S: S type M: M type L: L type	Grease type No entry: Standard GC: Clean	Stroke^{Note 3} Horizontal (100mm pitch) 100 to 3800 100 to 1800 (100mm pitch) Wall (100mm pitch)	Cable length 3L: 3.5m 5L: 5m 10L: 10m 3K/5K/10K (Flexible cable) ^{Note 5}	RCX221 Controller RCX221 SR1-P (2 units) TS-P (2 units) RDV-P (2 units)	Usable for CE No entry: Standard E: CE marking	I/O selection 1 N: NPN P: PNP CC: CC-Link DN: DeviceNet™ PB: PROFIBUS EN: Ethernet	I/O selection 2 No entry: None N1: OPDI024/16 (NPN) P1: OPDI024/17 (PNP) EN: Ethernet
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Specifications

Model	MF7	MF7D
Driving method	Steel cored linear motor with falt magnet	
Repeatability (µm)	+/-5	
Scale (µm)	Magnetic type: resolution of 1	
Maximum speed^{Note 2} (mm/sec)	2500	
Rated thrust (N)	37	
Maximum payload (kg)	10 ^{Note 1}	
Stroke (mm)	Horizontal	100 to 4000 (100mm pitch)
	Wall mount	100 to 1800 (100mm pitch)
Linear guide	4 rows of circular arc grooves × 1 rail	
Maximum cross-section outside dimensions (mm)	W85 × H80 (except the cable carrier section)	
Total length (mm)	Stroke+280	Stroke+480
Cable length (m)	Standard: 3.5 / Option: 5.10	

Note. A vertical model (with brake) is not available with the PHASER series.
 Note. The basic specifications of semi-absolute model are the same as those of the incremental model.
 Note 1. Payload per carrier. When the payload exceeds 7kg, please consult our sales office or sales representative.
 Note 2. Table of maximum speed



Allowable overhang

	Horizontal installation (Unit: mm)			Wall installation (Unit: mm)		
	A	B	C	A	B	C
1kg	3000	3000	680	700	3000	3000
3kg	3000	1350	215	195	1260	3000
5kg	2900	830	125	90	630	2480
7kg	2400	580	85	50	360	1680
9kg	2200	460	60			
10kg	2100	410	55			

Note. Distance from center of slider top to center of gravity of object being carried at a guide service life of 10,000 km.

Static loading moment

MY	MP	MR
156	156	194

(Unit: N·m)

Controller

Controller	Operating method
SR1-P10	Programming / I/O point trace / Remote command / Operation using RS-232C communication
RCX221 RCX240/340	Operation using RS-232C communication
TS-P110	I/O point trace / Remote command
TS-P210	Remote command
RDV-P210-RBR1	Pulse train control

Cable carrier entry location

Note. Be sure to install in the direction as specified (in cable carrier take-out direction drawing and various specification drawings) individually. Installation in any other way will cause a failure. For requirement of installation in any way other than the above standard installation, please consult YAMAHA as a special arrangement will be available.

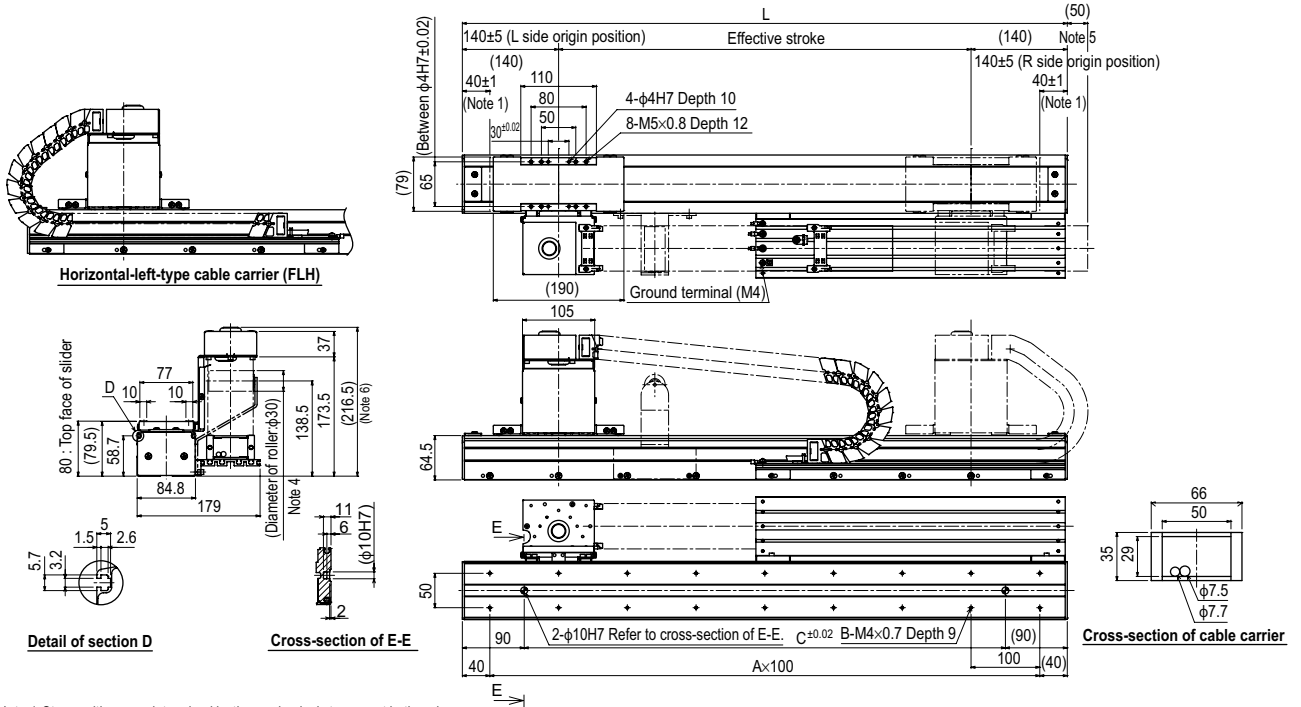
Optional cable carrier for users

Cable and air tube guide

S: φ8 flexible cable x 1, φ4 air tube x 1
 M: φ8 flexible cable x 2, φ6 air tube x 2
 L: φ8 flexible cable x 2, φ8 air tube x 3

Space for optional cable for users

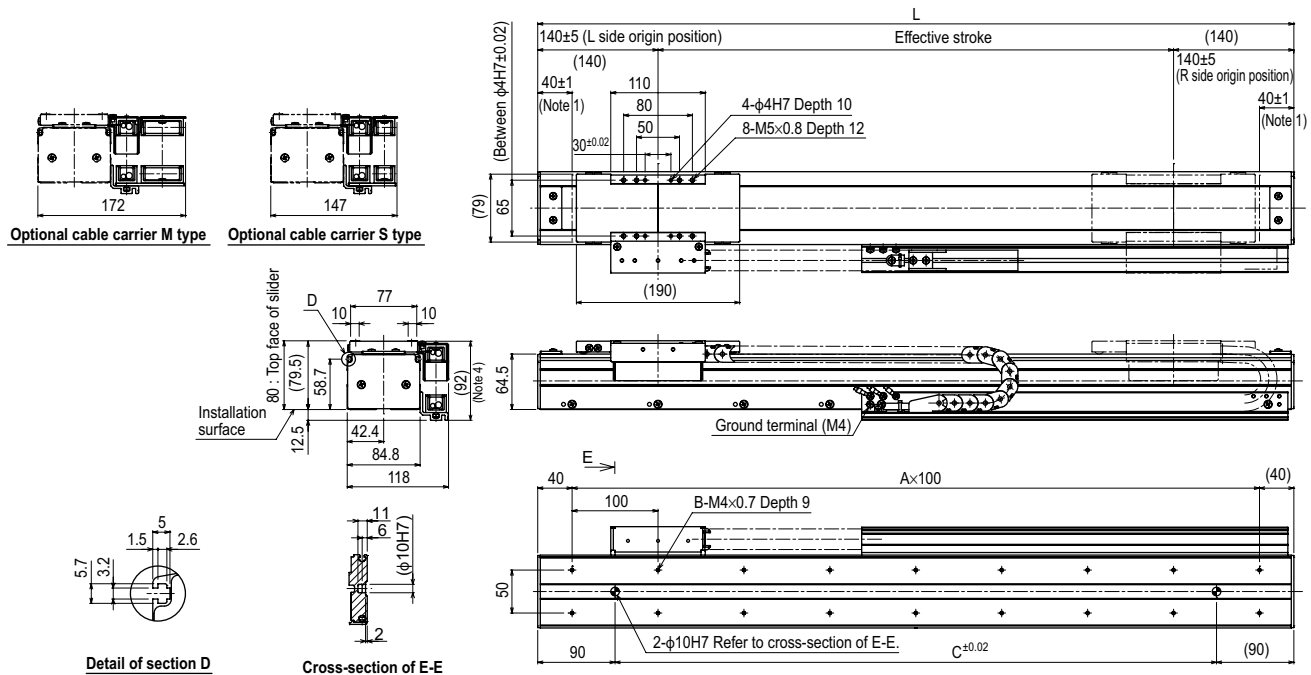
MF7 single carriage horizontal mount model **RH-L** Optional L-type cable carrier



Note 1. Stop positions are determined by the mechanical stoppers at both ends.
 Note 2. The origin is set on the L side at the time of shipment. It can be changed to the R side by parameter setting.
 Note 3. The drawings on this page show the unit with horizontal-right-type cable carrier (RH).
 Note 4. For models with a 3,000mm or longer stroke, a roller is installed to prevent the cable carrier from sagging.
 Note 5. Protrusion is the distance the cable carrier extends from the edge of the unit.
 Note 6. Depending on the stroke and the operating conditions, the cable carrier bending radius might be larger, making it higher than the dimensions shown in the diagram.

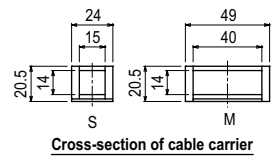
Effective stroke	100	200	300	400	500	600	700	800	900	1000	1100	1200	1300	1400	1500	1600	1700	1800	1900	2000	2100	2200	2300	2400	2500	2600	2700	2800	2900	3000	3100	3200	3300	3400	3500	3600	3700	3800	3900	4000
L	380	480	580	680	780	880	980	1080	1180	1280	1380	1480	1580	1680	1780	1880	1980	2080	2180	2280	2380	2480	2580	2680	2780	2880	2980	3080	3180	3280	3380	3480	3580	3680	3780	3880	3980	4080	4180	4280
A	3	4	5	6	7	8	9	10	11	12	13	14	15	16	17	18	19	20	21	22	23	24	25	26	27	28	29	30	31	32	33	34	35	36	37	38	39	40	41	42
B	8	10	12	14	16	18	20	22	24	26	28	30	32	34	36	38	40	42	44	46	48	50	52	54	56	58	60	62	64	66	68	70	72	74	76	78	80	82	84	86
C	200	300	400	500	600	700	800	900	1000	1100	1200	1300	1400	1500	1600	1700	1800	1900	2000	2100	2200	2300	2400	2500	2600	2700	2800	2900	3000	3100	3200	3300	3400	3500	3600	3700	3800	3900	4000	4100
Weight (kg)	5.8	6.5	7.3	8.0	8.7	9.4	10.1	10.9	11.6	12.3	13.0	13.7	14.5	15.2	15.9	16.6	17.3	18.1	18.8	19.5	20.2	20.9	21.7	22.4	23.1	23.8	24.5	25.3	26.0	26.7	27.4	28.1	28.9	29.6	30.3	31.0	31.7	32.5	33.2	33.9

MF7 single carriage horizontal mount model **FRH** Flat type



Note 1. Stop positions are determined by the mechanical stoppers at both ends.
 Note 2. The origin is set on the L side at the time of shipment. It can be changed to the R side by parameter setting.
 Note 3. The drawings on this page show the unit with horizontal-right-type cable carrier (RH).
 Note 4. Depending on the stroke and the operating conditions, the cable carrier bending radius might be larger, making it higher than the dimensions shown in the diagram.

Effective stroke	100	200	300	400	500	600	700	800	900	1000	1100	1200	1300	1400	1500	1600	1700	1800	1900	2000
L	380	480	580	680	780	880	980	1080	1180	1280	1380	1480	1580	1680	1780	1880	1980	2080	2180	2280
A	3	4	5	6	7	8	9	10	11	12	13	14	15	16	17	18	19	20	21	22
B	8	10	12	14	16	18	20	22	24	26	28	30	32	34	36	38	40	42	44	46
C	200	300	400	500	600	700	800	900	1000	1100	1200	1300	1400	1500	1600	1700	1800	1900	2000	2100
Weight (kg)	5.8	6.5	7.3	8	8.7	9.4	10.1	10.9	11.6	12.3	13	13.7	14.5	15.2	15.9	16.6	17.3	18.1	18.8	19.5



MF7D double carriage horizontal mount model **H**

Optional cable carrier M type **Optional cable carrier S type**

Detail of section D **Cross-section of E-E**

Cross-section of cable carrier

Effective stroke	100	200	300	400	500	600	700	800	900	1000	1100	1200	1300	1400	1500	1600	1700	1800	1900	2000
L	580	680	780	880	980	1080	1180	1280	1380	1480	1580	1680	1780	1880	1980	2080	2180	2280	2380	2480
A	5	6	7	8	9	10	11	12	13	14	15	16	17	18	19	20	21	22	23	24
B	12	14	16	18	20	22	24	26	28	30	32	34	36	38	40	42	44	46	48	50
C	400	500	600	700	800	900	1000	1100	1200	1300	1400	1500	1600	1700	1800	1900	2000	2100	2200	2300
Weight (kg)	9.3	10.2	11.1	12.0	12.9	13.9	14.8	15.7	16.6	17.5	18.5	19.4	20.3	21.2	22.1	23.1	24.0	24.9	25.8	26.7

Note 1. Position of the table slider when returned to the origin.
 Note 2. Stop positions are determined by the mechanical stoppers at both ends.
 Note 3. Depending on the stroke and the operating conditions, the cable carrier bending radius might be larger, making it higher than the dimensions shown in the diagram.

MF7D double carriage wall mount model **W**

Cross-section of optional cable carrier **Cross-section of F-F**

Detail of section G

Optional cable carrier L type **Optional cable carrier M type** **Standard and S types**

Cross-section of optional cable carrier **Cross-section of F-F**

Standard and L types **Standard and M types** **Standard and S types**

Effective stroke	100	200	300	400	500	600	700	800	900	1000	1100	1200	1300	1400	1500	1600	1700	1800
L	580	680	780	880	980	1080	1180	1280	1380	1480	1580	1680	1780	1880	1980	2080	2180	2280
A	5	6	7	8	9	10	11	12	13	14	15	16	17	18	19	20	21	22
B	12	14	16	18	20	22	24	26	28	30	32	34	36	38	40	42	44	46
C	400	500	600	700	800	900	1000	1100	1200	1300	1400	1500	1600	1700	1800	1900	2000	2100
D	220	270	320	370	420	470	520	570	620	670	720	770	820	870	920	970	1020	1070
Weight (kg)	9.3	10.2	11.1	12.0	12.9	13.9	14.8	15.7	16.6	17.5	18.5	19.4	20.3	21.2	22.1	23.1	24.0	24.9

Note 1. Stop positions are determined by the mechanical stoppers at both ends.
 Note 2. Cable carrier's protrusion amount from the mechanical end.
 Note 3. Depending on the stroke and the operating conditions, the cable carrier bending radius might be larger, making it higher than the dimensions shown in the diagram.

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Linear motor single-axis robots
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Cartesian robots
XX-X

SCARA robots
YK-X

Pick & place robots
YP-X

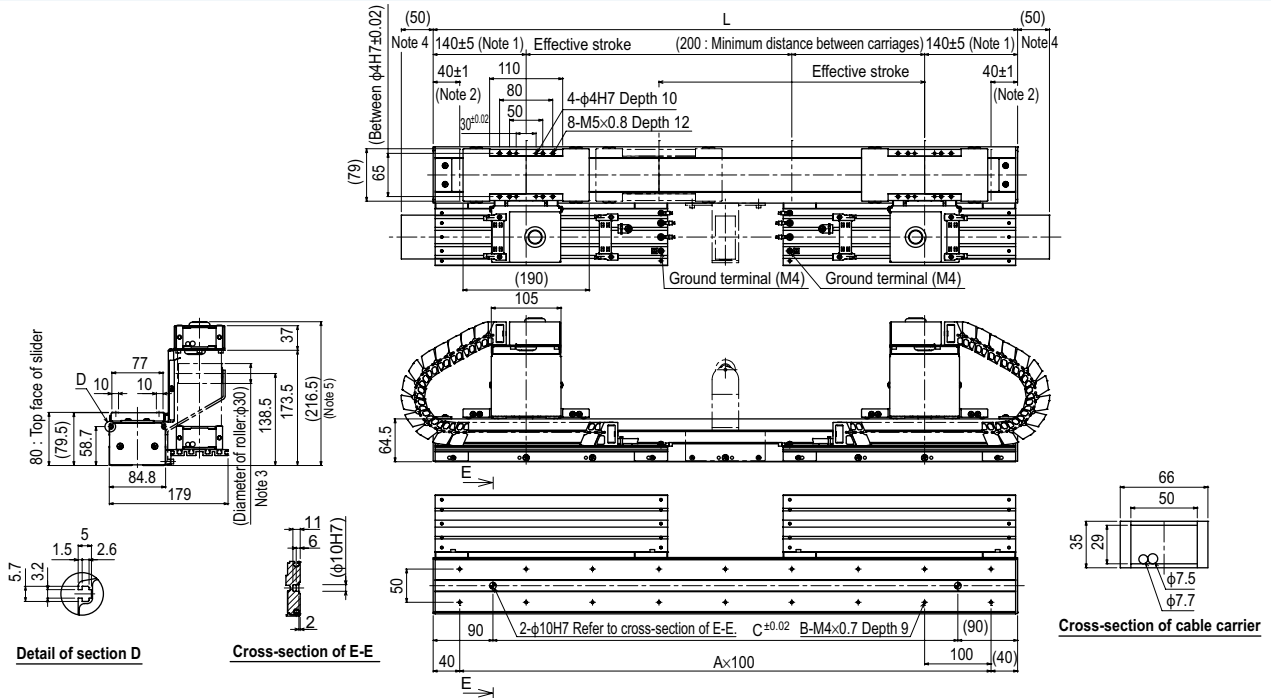
CLEAN

CONTROLLER INFORMATION

MF type

MR type

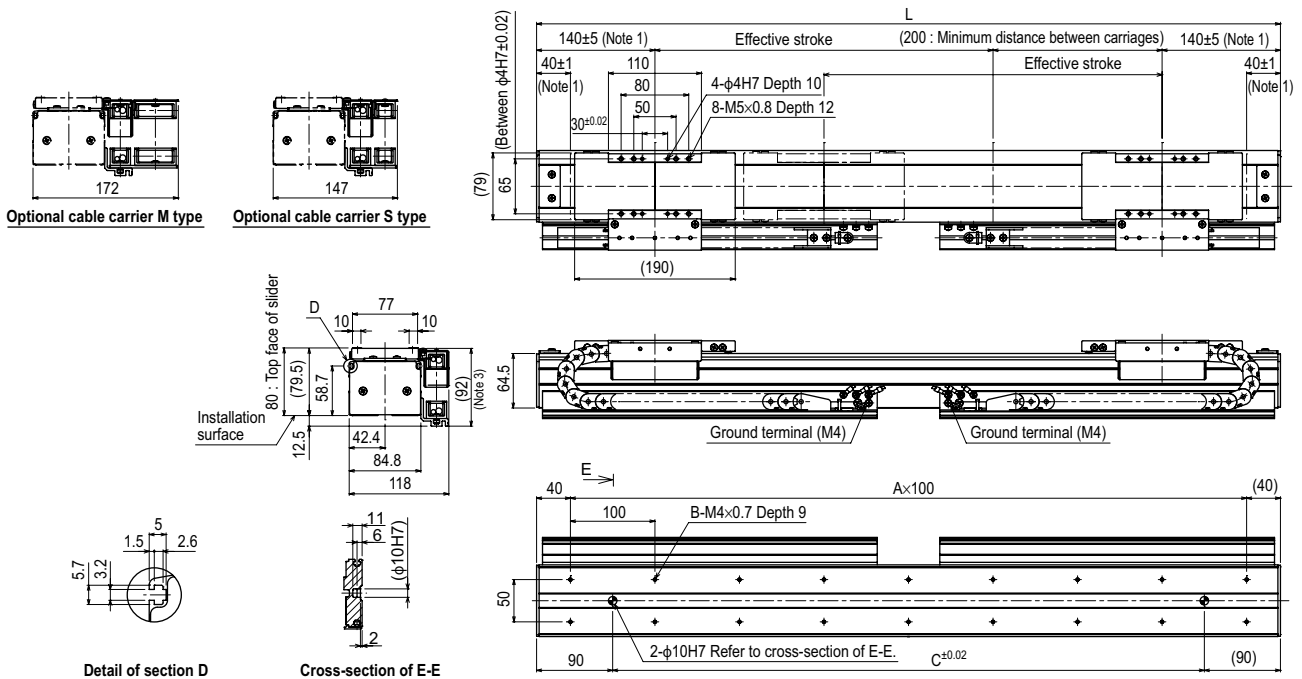
MF7D double carriage horizontal mount model **(H-L)** Optional L-type cable carrier



Note 1. Position of the table slider when returned to the origin.
 Note 2. Stop positions are determined by the mechanical stoppers at both ends.
 Note 3. For models with a 3,000mm or longer stroke, a roller is installed to prevent the cable carrier from sagging.
 Note 4. Protrusion is the distance the cable carrier extends from the edge of the unit.
 Note 5. Depending on the stroke and the operating conditions, the cable carrier bending radius might be larger, making it higher than the dimensions shown in the diagram.

Effective stroke	100	200	300	400	500	600	700	800	900	1000	1100	1200	1300	1400	1500	1600	1700	1800	1900	2000	2100	2200	2300	2400	2500	2600	2700	2800	2900	3000	3100	3200	3300	3400	3500	3600	3700	3800
L	580	680	780	880	980	1080	1180	1280	1380	1480	1580	1680	1780	1880	1980	2080	2180	2280	2380	2480	2580	2680	2780	2880	2980	3080	3180	3280	3380	3480	3580	3680	3780	3880	3980	4080	4180	4280
A	5	6	7	8	9	10	11	12	13	14	15	16	17	18	19	20	21	22	23	24	25	26	27	28	29	30	31	32	33	34	35	36	37	38	39	40	41	42
B	12	14	16	18	20	22	24	26	28	30	32	34	36	38	40	42	44	46	48	50	52	54	56	58	60	62	64	66	68	70	72	74	76	78	80	82	84	86
C	400	500	600	700	800	900	1000	1100	1200	1300	1400	1500	1600	1700	1800	1900	2000	2100	2200	2300	2400	2500	2600	2700	2800	2900	3000	3100	3200	3300	3400	3500	3600	3700	3800	3900	4000	4100
Weight (kg)	9.3	10.2	11.1	12.0	12.9	13.9	14.8	15.7	16.6	17.5	18.5	19.4	20.3	21.2	22.1	23.1	24.0	24.9	25.8	26.7	27.7	28.6	29.5	30.4	31.3	32.3	33.2	34.1	35.0	35.9	36.9	37.8	38.7	39.6	40.5	41.5	42.4	43.3

MF7D double carriage horizontal mount model **(FH)** Flat type



Note 1. Position of the table slider when returned to the origin.
 Note 2. Stop positions are determined by the mechanical stoppers at both ends.
 Note 3. Depending on the stroke and the operating conditions, the cable carrier bending radius might be larger, making it higher than the dimensions shown in the diagram.

Effective stroke	100	200	300	400	500	600	700	800	900	1000	1100	1200	1300	1400	1500	1600	1700	1800	1900	2000
L	580	680	780	880	980	1080	1180	1280	1380	1480	1580	1680	1780	1880	1980	2080	2180	2280	2380	2480
A	5	6	7	8	9	10	11	12	13	14	15	16	17	18	19	20	21	22	23	24
B	12	14	16	18	20	22	24	26	28	30	32	34	36	38	40	42	44	46	48	50
C	400	500	600	700	800	900	1000	1100	1200	1300	1400	1500	1600	1700	1800	1900	2000	2100	2200	2300
Weight (kg)	9.3	10.2	11.1	12.0	12.9	13.9	14.8	15.7	16.6	17.5	18.5	19.4	20.3	21.2	22.1	23.1	24.0	24.9	25.8	26.7

Articulated robots
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Single-axis robots
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Linear motor
single-axis robots
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Cartesian
robots
XY-X

SCARA
robots
YK-X

Pick & place
robots
YP-X

CLEAN

CONTROLLER

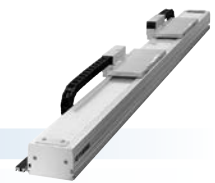
INFORMATION

MF type

MR type

MF15/MF15D

Can be used for wall-mount



Ordering method

Single carriage model

MF15

Model MF15: Incremental MF15A: Semi-absolute ^{Note 1}	Cable carrier entry location RH: Horizontal, right LH: Horizontal, left RW: Wall mount, right LW: Wall mount, left	Optional cable carrier for users^{Note 2} No entry: None S: S type M: M type L: L type	Origin position change Horizontal: No entry: L side (Standard) Z: R side Wall: No entry: R side (Standard) Z: L side	Grease type No entry: Standard GC: Clean	Stroke Horizontal: 100 to 4000 (100mm pitch) 100 to 2000 (100mm pitch) Wall: 100 to 2000 (100mm pitch)	Cable length^{Note 3} 3L: 3.5m 5L: 5m 10L: 10m 3K/5K/10K (Flexible cable) ^{Note 4}
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TSP

Positioner^{Note 5} TS-P	Driver: Power-supply voltage / Power capacity 110: 100V/200W 210: 200V/200W	LCD monitor No entry: None L: With LCD	I/O selection NP: NPN PN: PNP CC: CC-Link DN: DeviceNet™ EP: EtherNet/IP™ GW: No I/O board ^{Note 6}
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SR1-P 10

Controller	Driver: Power capacity 10: 200W	Usable for CE No entry: Standard E: CE marking	I/O selection N: NPN P: PNP CC: CC-Link DN: DeviceNet™ PB: PROFIBUS
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RDV-P 2 10 RBR1

Driver	Power-supply voltage 2: AC200V	Driver: Power capacity 10: 200W or less	Regenerative unit RBR1
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Note 1. For the details of the semi-absolute model, please refer to P.33. RDV-P has an incremental model only.
 Note 2. For models with a 2,100mm or longer stroke, optional L type cable carriers can only be used.
 Note 3. The robot cable is standard cable (3L/5L/10L), but can be changed to flexible cable. See P.594 for details on robot cable.
 Note 4. If a flexible cable is needed for the SR1-P, TS-P, or RDV-P, then select 3K/5K/10K. On the RCX221, the standard cable is a flexible cable, so enter 3L/5L/10L when ordering.
 Note 5. These controllers can be mounted on DIN rails. See P.498 for details.
 Note 6. Select this selection when using the gateway function. For details, see P.60.
 Note. It is possible to provide the model without a cable carrier. To find information on wiring (cable terminals) within the cable carrier see P.602.

Double carriage model

MF15D

Model MF15D: Incremental MF15AD: Semi-absolute ^{Note 1}	Installing direction H: Horizontal installation W: Wall mount installation	Optional cable carrier for users^{Note 2} No entry: None S: S type M: M type L: L type	Grease type No entry: Standard GC: Clean	Stroke Horizontal: 100 to 3800 (100mm pitch) 100 to 1800 (100mm pitch) Wall: 100 to 1800 (100mm pitch)	Cable length 3L: 3.5m 5L: 5m 10L: 10m 3K/5K/10K (Flexible cable) ^{Note 4}
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RCX221

Controller RCX221 SR1-P (2 units) TS-P (2 units) RDV-P (2 units)	Usable for CE No entry: Standard E: CE marking	I/O selection 1 N: NPN P: PNP CC: CC-Link DN: DeviceNet™ PB: PROFIBUS EN: Ethernet	I/O selection 2 No entry: None NT: OPDIO24/16 (NPN) PT: OPDIO24/17 (PNP) EN: Ethernet
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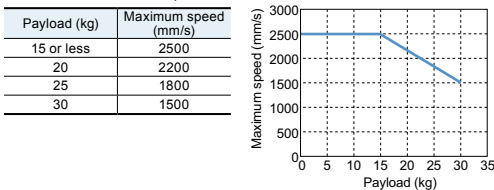
Specifications

Model	MF15	MF15D
Driving method	Steel cored linear motor with falt magnet	
Repeatability (µm)	+/-5	
Scale (µm)	Magnetic type: resolution of 1	
Maximum speed^{Note 2} (mm/sec)	2500	
Rated thrust (N)	54	
Maximum payload^{Note 1} (kg)	30	
Stroke (mm)	Horizontal	100 to 4000 (100mm pitch) / 100 to 3800 (100mm pitch)
	Wall mount	100 to 2000 (100mm pitch) / 100 to 1800 (100mm pitch)
Linear guide	4 rows of circular arc grooves x 2 rail	
Maximum cross-section outside dimensions (mm)	W100 x H80 (except the cable carrier section)	
Total length (mm)	Stroke+260	Stroke+460
Cable length (m)	Standard: 3.5 / Option: 5,10	

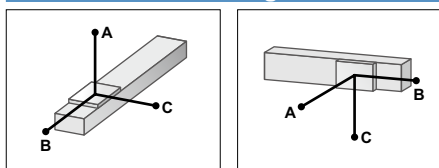
Note. A vertical model (with brake) is not available with the PHASER series.
 Note. The basic specifications of semi-absolute model are the same as those of the incremental model.

Note 1. Payload per carrier. When the payload exceeds 15kg, please consult our sales office or sales representative.

Note 2. Table of maximum speed



Allowable overhang



Horizontal installation (Unit: mm)

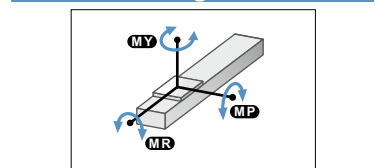
	A	B	C
5kg	3000	3000	915
10kg	2604	1542	481
15kg	2368	1051	340
20kg	1820	600	260
25kg	1470	450	175
30kg	1250	310	145

Wall installation (Unit: mm)

	A	B	C
5kg	865	1880	3060
10kg	410	905	2115
15kg	255	575	1910
20kg	170	410	1780
25kg	120	295	1660
30kg	90	215	1440

Note. Distance from center of slider top to center of gravity of object being carried at a guide service life of 10,000 km.

Static loading moment

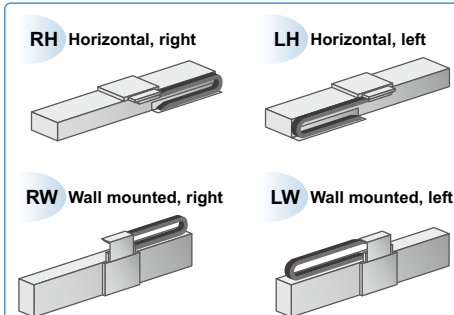


	MY	MP	MR
(Unit: N·m)	290	291	256

Controller

Controller	Operating method
SR1-P10	Programming / I/O point trace / Remote command / Operation using RS-232C communication
RCX221 RCX240/340	Operation using RS-232C communication
TS-P110	I/O point trace / Remote command
TS-P210	Remote command
RDV-P210-RBR1	Pulse train control

Cable carrier entry location



Note. Be sure to install in the direction as specified (in cable carrier take-out direction drawing and various specification drawings) individually. Installation in any other way will cause a failure. For requirement of installation in any way other than the above standard installation, please consult YAMAHA as a special arrangement will be available.

Optional cable carrier for users

S type

M type

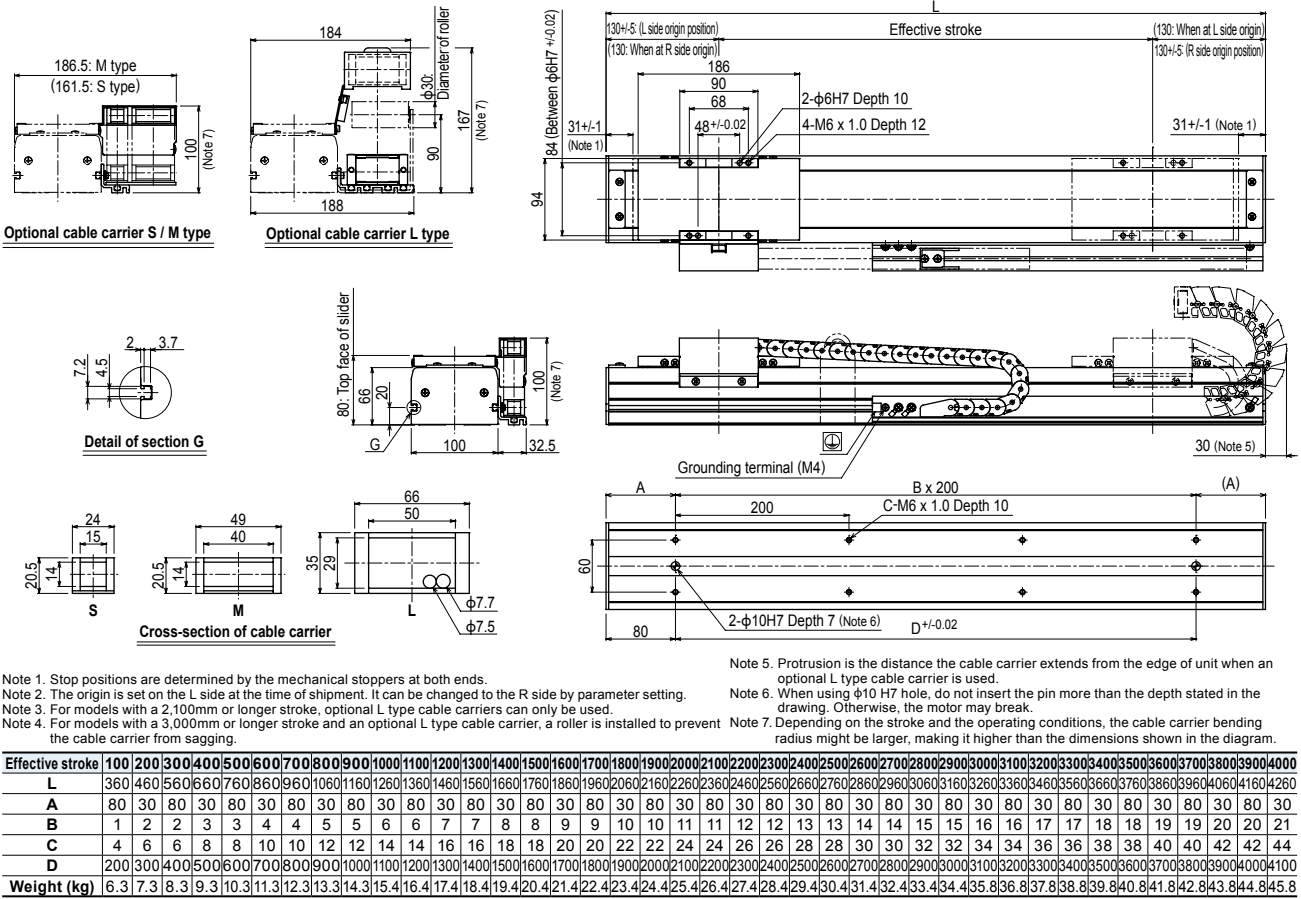
L type

Cable and air tube guide

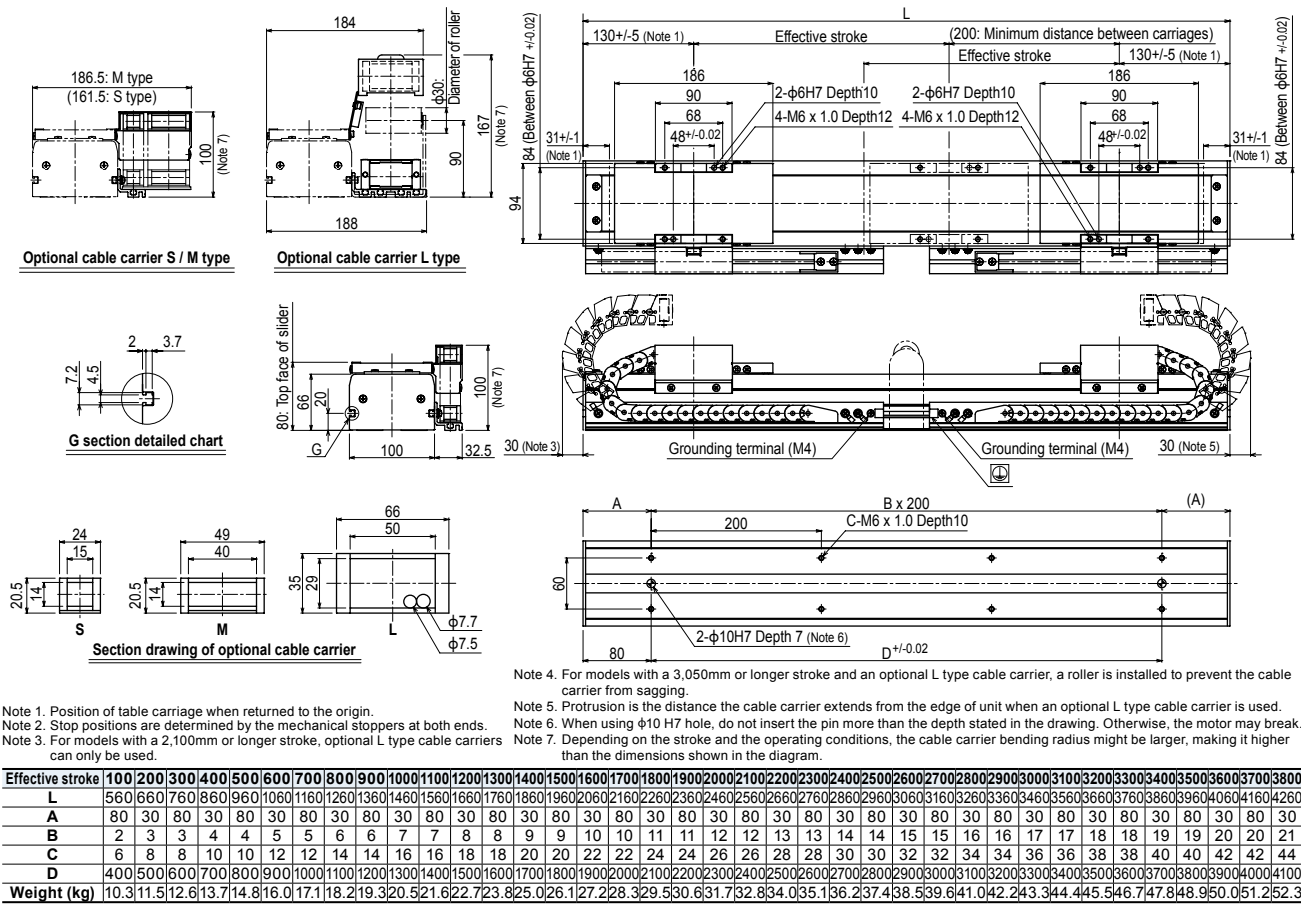
S: φ8 flexible cable x 1, φ4 air tube x 1
 M: φ8 flexible cable x 2, φ6 air tube x 2
 L: φ8 flexible cable x 2, φ8 air tube x 3

Space for optional cable for users

MF15 single carriage horizontal mount model **RH**



MF15D double carriage horizontal mount model **H**



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Linear motor single-axis robots
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Cartesian robots
XX-X

SCARA robots
YK-X

Pick & place robots
YP-X

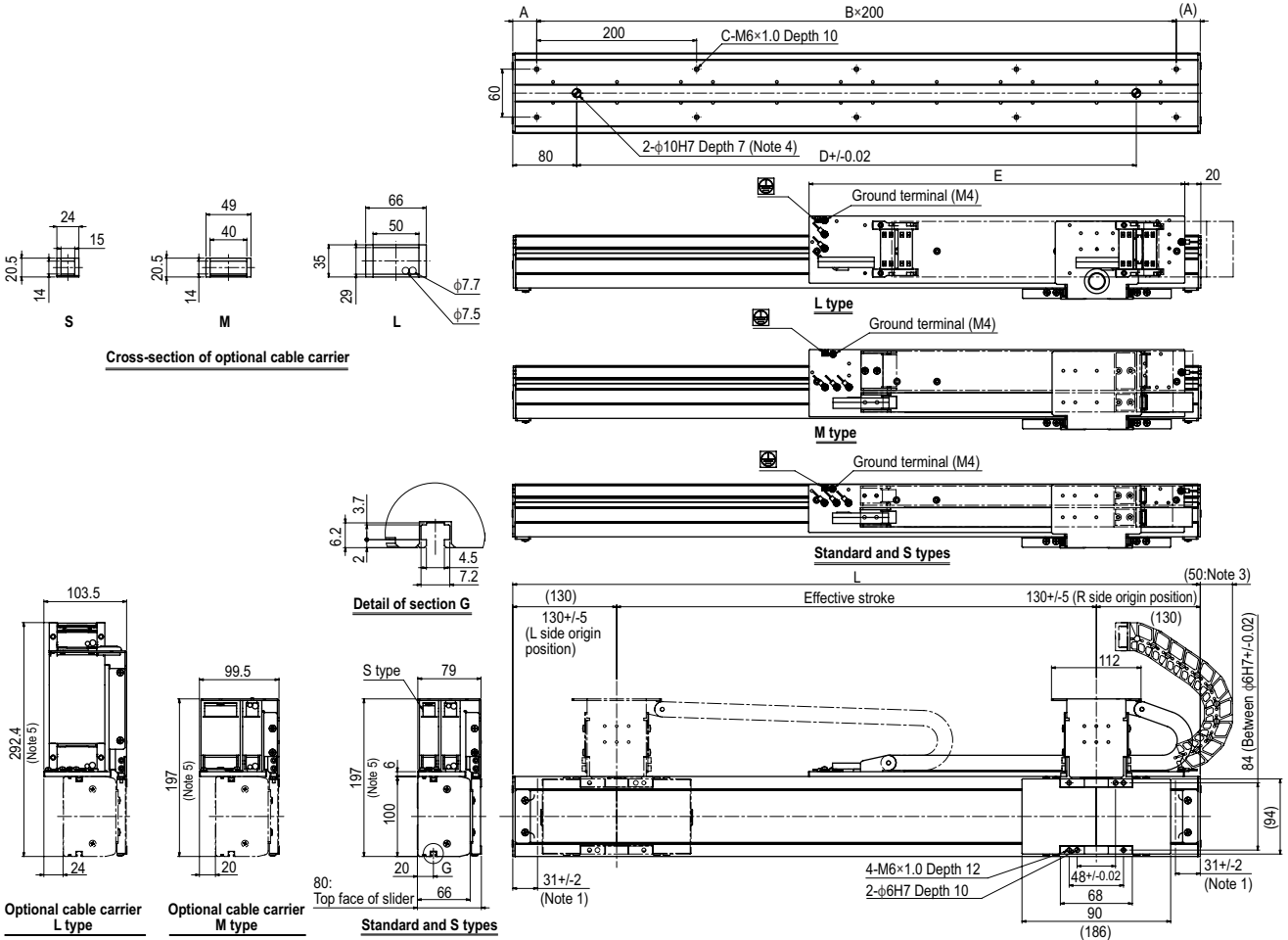
CLEAN

CONTROLLER INFORMATION

MF type

MR type

MF15 single carriage wall mount model RW

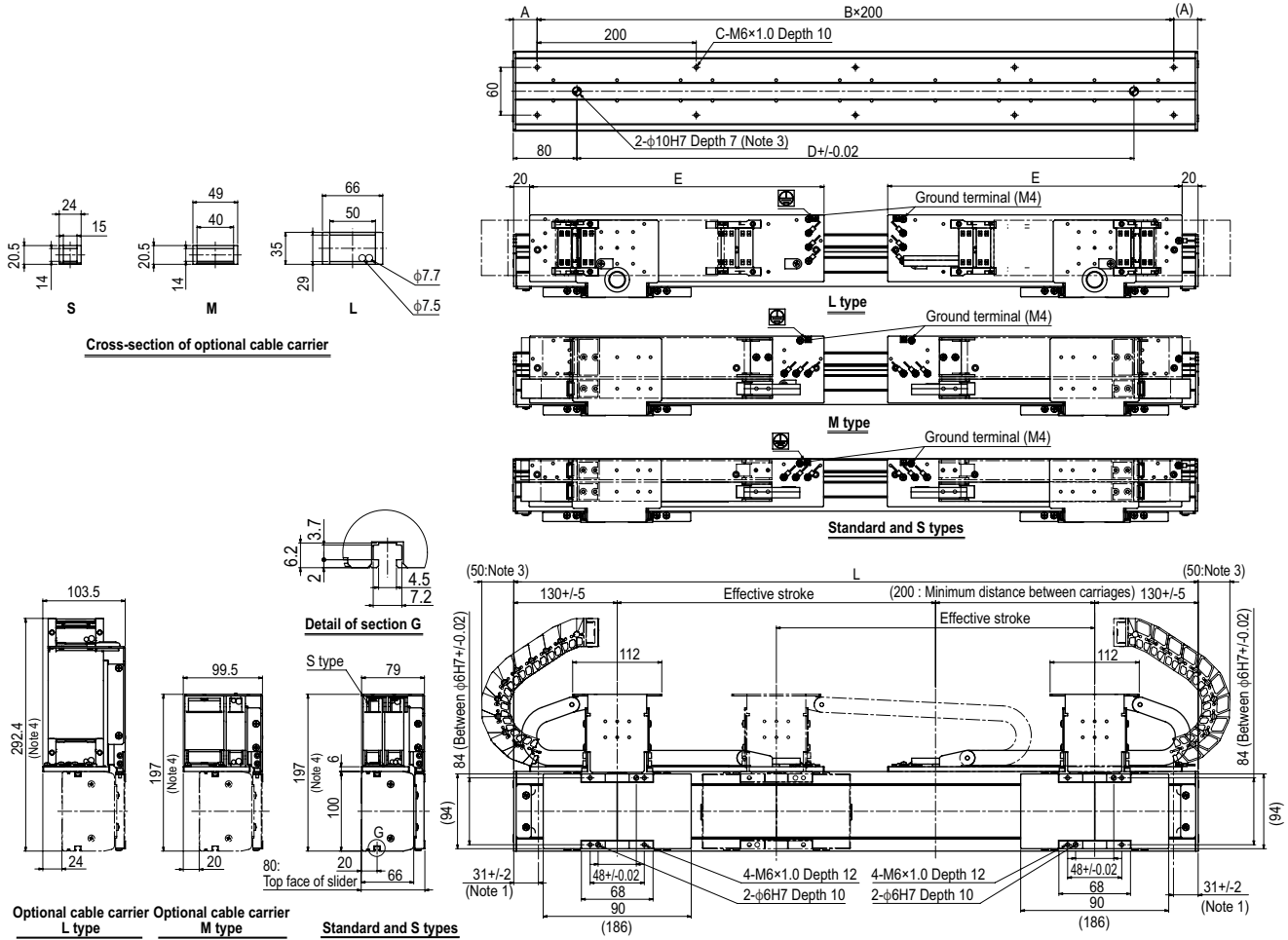


Note 1. Stop positions are determined by the mechanical stoppers at both ends.
 Note 2. The origin is set on the R side at the time of shipment. It can be changed to the L side by parameter setting.
 Note 3. Protrusion is the distance the cable carrier extends from the edge of unit when an optional L type cable carrier is used.
 Note 4. When using $\phi 10$ H7 hole, do not insert the pin more than the depth stated in the drawing. Otherwise, the motor may break.
 Note 5. Depending on the stroke and the operating conditions, the cable carrier bending radius might be larger, making it higher than the dimensions shown in the diagram.

Effective stroke	100	200	300	400	500	600	700	800	900	1000	1100	1200	1300	1400	1500	1600	1700	1800	1900	2000
L	360	460	560	660	760	860	960	1060	1160	1260	1360	1460	1560	1660	1760	1860	1960	2060	2160	2260
A	80	30	80	30	80	30	80	30	80	30	80	30	80	30	80	30	80	30	80	30
B	1	2	2	3	3	4	4	5	5	6	6	7	7	8	8	9	9	10	10	11
C	4	6	6	8	8	10	10	12	12	14	14	16	16	18	18	20	20	22	22	24
D	200	300	400	500	600	700	800	900	1000	1100	1200	1300	1400	1500	1600	1700	1800	1900	2000	2100
E	220	270	320	370	420	470	520	570	620	670	720	770	820	870	920	970	1020	1070	1120	1170
Weight (kg)	6.3	7.3	8.3	9.3	10.3	11.3	12.3	13.3	14.3	15.4	16.4	17.4	18.4	19.4	20.4	21.4	22.4	23.4	24.4	25.4

MF15D double carriage wall mount model

W



Note 1. Stop positions are determined by the mechanical stoppers at both ends.
 Note 2. Protrusion is the distance the cable carrier extends from the edge of unit when an optional L type cable carrier is used.
 Note 3. When using φ10 H7 hole, do not insert the pin more than the depth stated in the drawing. Otherwise, the motor may break.
 Note 4. Depending on the stroke and the operating conditions, the cable carrier bending radius might be larger, making it higher than the dimensions shown in the diagram.

Effective stroke	100	200	300	400	500	600	700	800	900	1000	1100	1200	1300	1400	1500	1600	1700	1800
L	560	660	760	860	960	1060	1160	1260	1360	1460	1560	1660	1760	1860	1960	2060	2160	2260
A	80	30	80	30	80	30	80	30	80	30	80	30	80	30	80	30	80	30
B	2	3	3	4	4	5	5	6	6	7	7	8	8	9	9	10	10	11
C	6	8	8	10	10	12	12	14	14	16	16	18	18	20	20	22	22	24
D	400	500	600	700	800	900	1000	1100	1200	1300	1400	1500	1600	1700	1800	1900	2000	2100
E	220	270	320	370	420	470	520	570	620	670	720	770	820	870	920	970	1020	1070
Weight (kg)	10.3	11.5	12.6	13.7	14.8	16.0	17.1	18.2	19.3	20.5	21.6	22.7	23.8	25.0	26.1	27.2	28.3	29.5

Articulated robots
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Linear conveyor modules
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Compact single-axis robots
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Single-axis robots
FLIP-X

Linear motor single-axis robots
PHASER

Cartesian robots
XX-X

SCARA robots
YK-X

Pick & place robots
YP-X

CLEAN

CONTROLLER INFORMATION

MF type

MR type

MF20/MF20D

Can be used for wall-mount



Ordering method

Single carriage model

MF20

Model	Cable carrier entry location	Optional cable carrier for users ^{Note 2}	Origin position change	Grease type	Stroke	Cable length ^{Note 3}
MF20: Incremental MF20AD: Semi-absolute ^{Note 1}	RH: Horizontal, right LH: Horizontal, left RW: Wall mount, right LW: Wall mount, left	No entry: None S: S type M: M type L: L type	No entry: L side (Standard) Z: R side No entry: R side (Standard) Z: L side	No entry: Standard GC: Clean	150 to 4050 (100mm pitch)	3L: 3.5m 5L: 5m 10L: 10m 3K/5K/10K (Flexible cable) ^{Note 4}

TSP

Positioner ^{Note 5}	Driver: Power-supply voltage / Power capacity	Regenerative unit	LCD monitor	I/O selection
TS-P	110: 100V/200W 210: 200V/200W	R: With RGT	No entry: None L: With LCD	N: NPN PN: PNP CC: CC-Link DN: DeviceNet™ EP: EtherNet/IP™ GW: No I/O board ^{Note 6}

SR1-P 10

Controller	Driver: Power capacity	Usable for CE	Regenerative unit	I/O selection
	10: 200W	No entry: Standard E: CE marking	R: With RGT1	N: NPN P: PNP CC: CC-Link DN: DeviceNet™ PB: PROFIBUS

RDV-P 2 10 RBR1

Driver	Power-supply voltage	Driver: Power capacity	Regenerative unit
	2: AC200V	10: 200W or less	

- Note 1. For the details of the semi-absolute model, please refer to P.33. RDV-P has an incremental model only.
- Note 2. For models with a 2,050mm or longer stroke, optional L type cable carriers can only be used.
- Note 3. The robot cable is standard cable (3L/5L/10L), but can be changed to flexible cable. See P.594 for details on robot cable.
- Note 4. If a flexible cable is needed for the SR1-P, TS-P, or RDV-P, then select 3K/5K/10K. On the RCX221, the standard cable is a flexible cable, so enter 3L/5L/10L when ordering.
- Note 5. These controllers can be mounted on DIN rails. See P.498 for details.
- Note 6. Select this selection when using the gateway function. For details, see P.60.
- Note. It is possible to provide the model without a cable carrier. To find information on wiring (cable terminals) within the cable carrier see P.602.

Double carriage model

MF20D

Model	Installing direction	Optional cable carrier for users ^{Note 2}	Grease type	Stroke	Cable length	Controller	Usable for CE	Regenerative unit	I/O selection 1	I/O selection 2
MF20D: Incremental MF20AD: Semi-absolute ^{Note 1}	H: Horizontal installation W: Wall mount installation	No entry: None S: S type M: M type L: L type	No entry: Standard GC: Clean	150 to 3850 (100mm pitch)	3L: 3.5m 5L: 5m 10L: 10m 3K/5K/10K (Flexible cable) ^{Note 4}	RCX221 SR1-P (2 units) TS-P (2 units) RDV-P (2 units)	No entry: Standard E: CE marking	R: RG2 (RCX221)	N: NPN P: PNP CC: CC-Link DN: DeviceNet™ PB: PROFIBUS EN: Ethernet	No entry: None NI: OP.DIO24/16 (NPN) PI: OP.DIO24/17 (PNP) EN: Ethernet

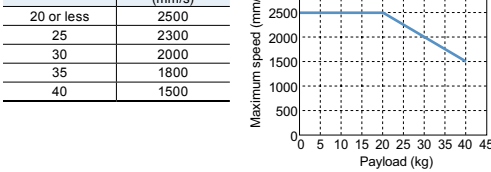
Specifications

Model	MF20	MF20D
Driving method	Steel cored linear motor with falt magnet	
Repeatability (µm)	+/-5	
Scale (µm)	Magnetic type: resolution of 1	
Maximum speed ^{Note 2} (mm/sec)	2500	
Rated thrust (N)	86	
Maximum payload ^{Note 1} (kg)	40	
Stroke (mm)	150 to 4050 (100mm pitch)	150 to 3850 (100mm pitch)
Linear guide	4 rows of circular arc grooves x 2 rail	
Maximum cross-section outside dimensions (mm)	W150 x H80 (except the cable carrier section)	
Total length (mm)	Stroke+260	Stroke+460
Cable length (m)	Standard: 3.5 / Option: 5.10	

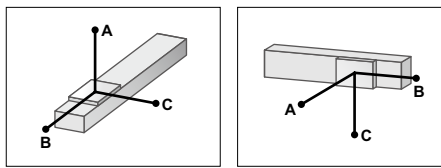
Note. A vertical model (with brake) is not available with the PHASER series.
Note. The basic specifications of semi-absolute model are the same as those of the incremental model.

Note 1. Payload per carrier. When the payload exceeds 20kg, please consult our sales office or sales representative.

Note 2. Table of maximum speed



Allowable overhang



	Horizontal installation (Unit: mm)			Wall installation (Unit: mm)			
	A	B	C	A	B	C	
10kg	3156	1747	1196	10kg	1220	1320	2540
15kg	2811	1176	883	15kg	870	850	2200
20kg	2679	890	717	20kg	670	610	2030
25kg	2190	720	505	25kg	485	400	1280
30kg	1830	605	370	30kg	350	325	1050
35kg	1580	525	275	35kg	265	270	890
40kg	1390	465	225	40kg	235	230	765

Note. Distance from center of slider top to center of gravity of object being carried at a guide service life of 10,000 km.

Static loading moment

MY	MP	MR
373	373	328

(Unit: N·m)

Controller

Controller	Operating method
SR1-P10-R	Programming / I/O point trace / Remote command / Operation using RS-232C communication
RCX221-R RCX240/340	Operation using RS-232C communication
TS-P110-R	I/O point trace / Remote command
TS-P210-R	Remote command
RDV-P210-RBR1	Pulse train control

Cable carrier entry location

RH Horizontal, right **LH** Horizontal, left

RW Wall mounted, right **LW** Wall mounted, left

Note. Be sure to install in the direction as specified (in cable carrier take-out direction drawing and various specification drawings) individually. Installation in any other way will cause a failure. For requirement of installation in any way other than the above standard installation, please consult YAMAHA as special arrangement will be available.

Optional cable carrier for users

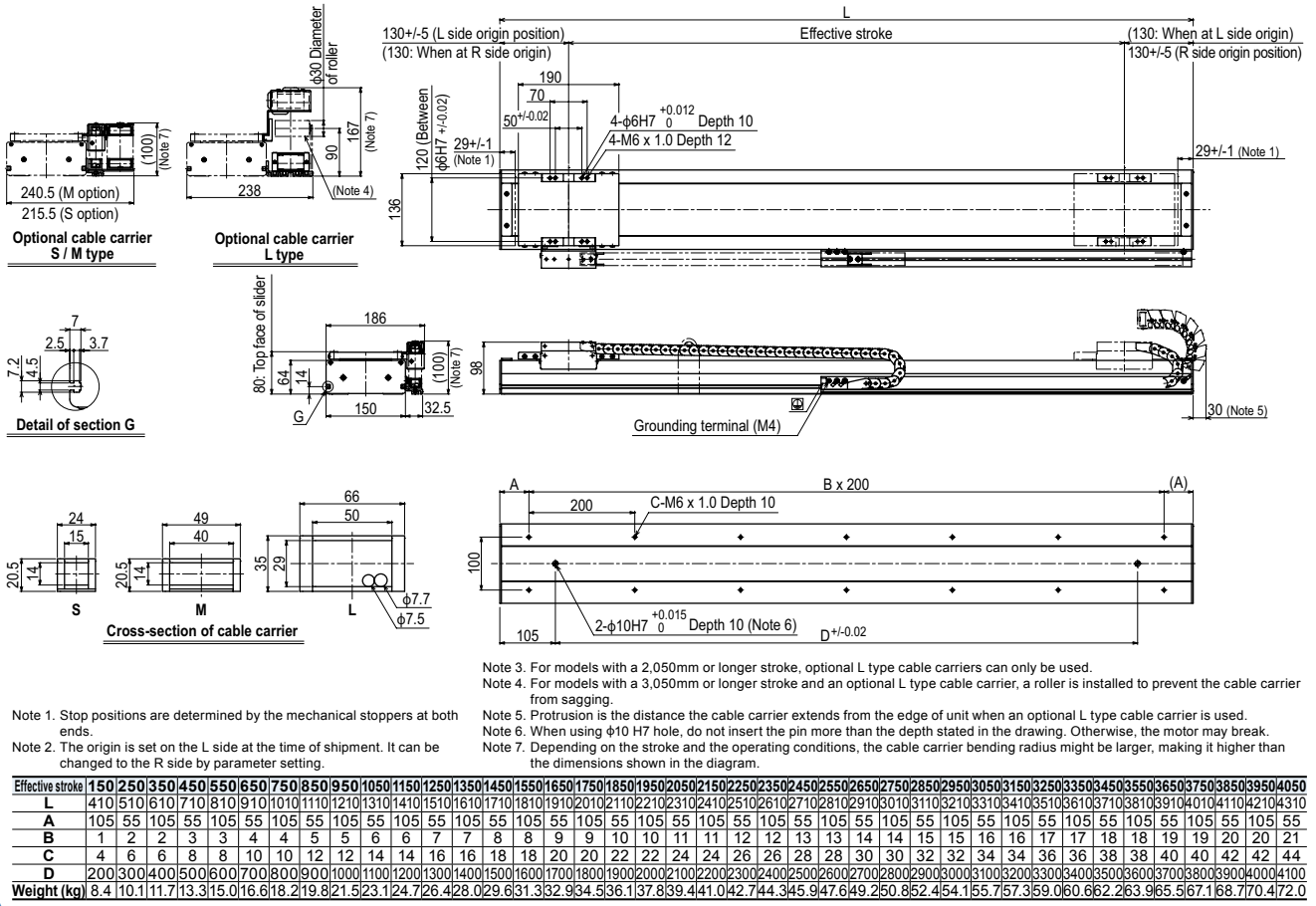
S type **M type** **L type**

Cable and air tube guide

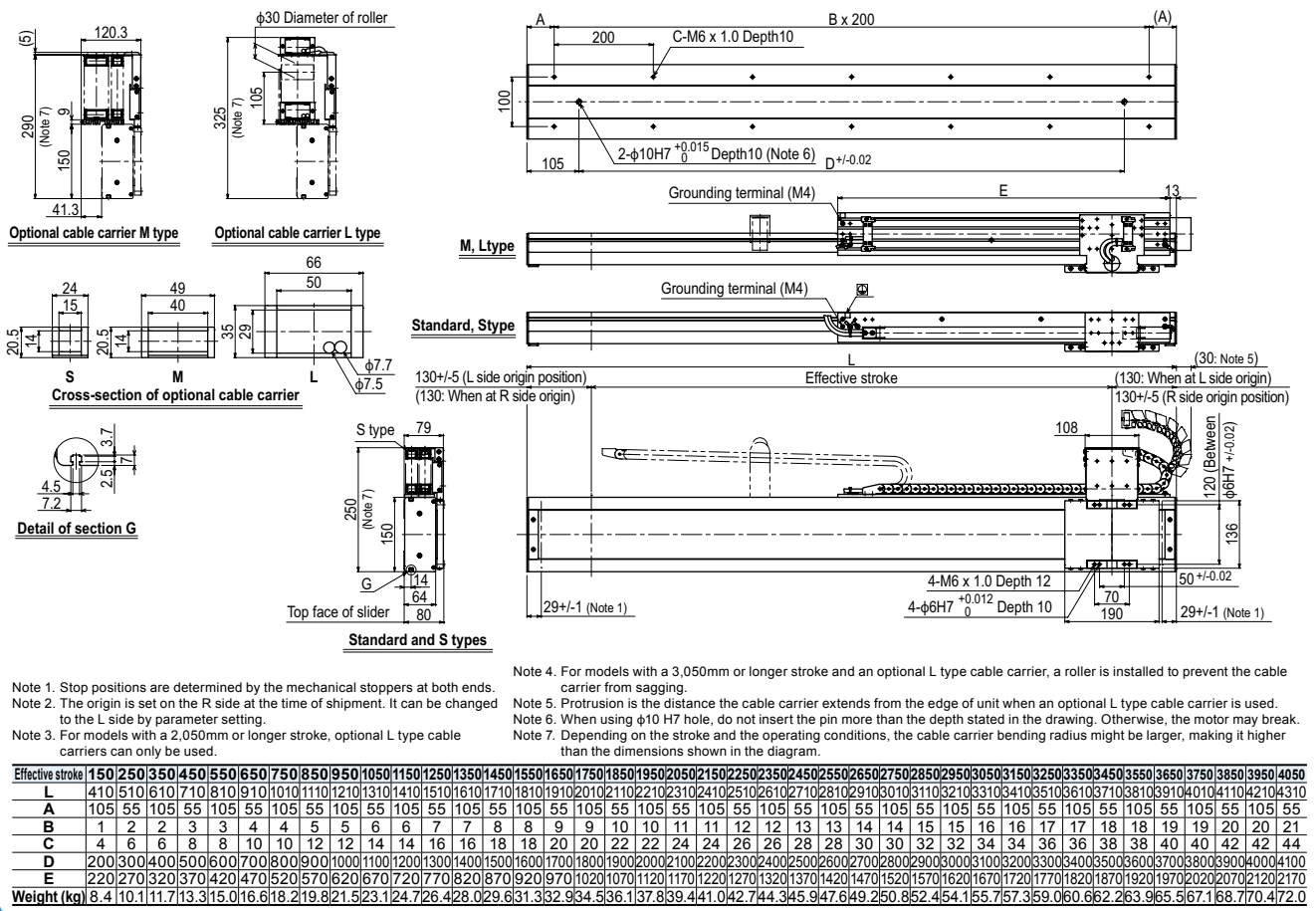
S: φ8 flexible cable x 1, φ4 air tube x 1
M: φ8 flexible cable x 2, φ6 air tube x 2
L: φ8 flexible cable x 2, φ8 air tube x 3

Space for optional cable for users

MF20 single carriage horizontal mount model **RH**



MF20 single carriage wall mount model **RW**



Articulated robots
YA

Linear conveyor modules
LCM100

Compact single-axis robots
TRANSEVO

Single-axis robots
FLIP-X

Linear motor single-axis robots
PHASER

Cartesian robots
XX-X

SCARA robots
YK-X

Pick & place robots
YP-X

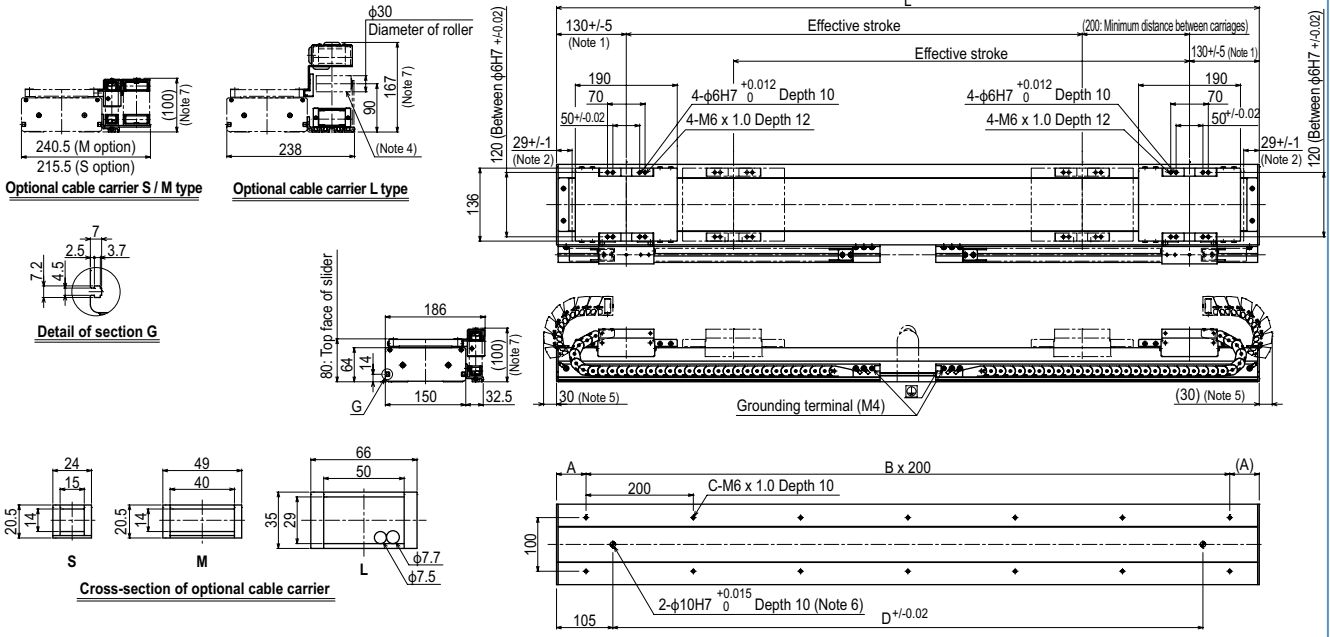
CLEAN

CONTROLLER INFORMATION

MF type

MR type

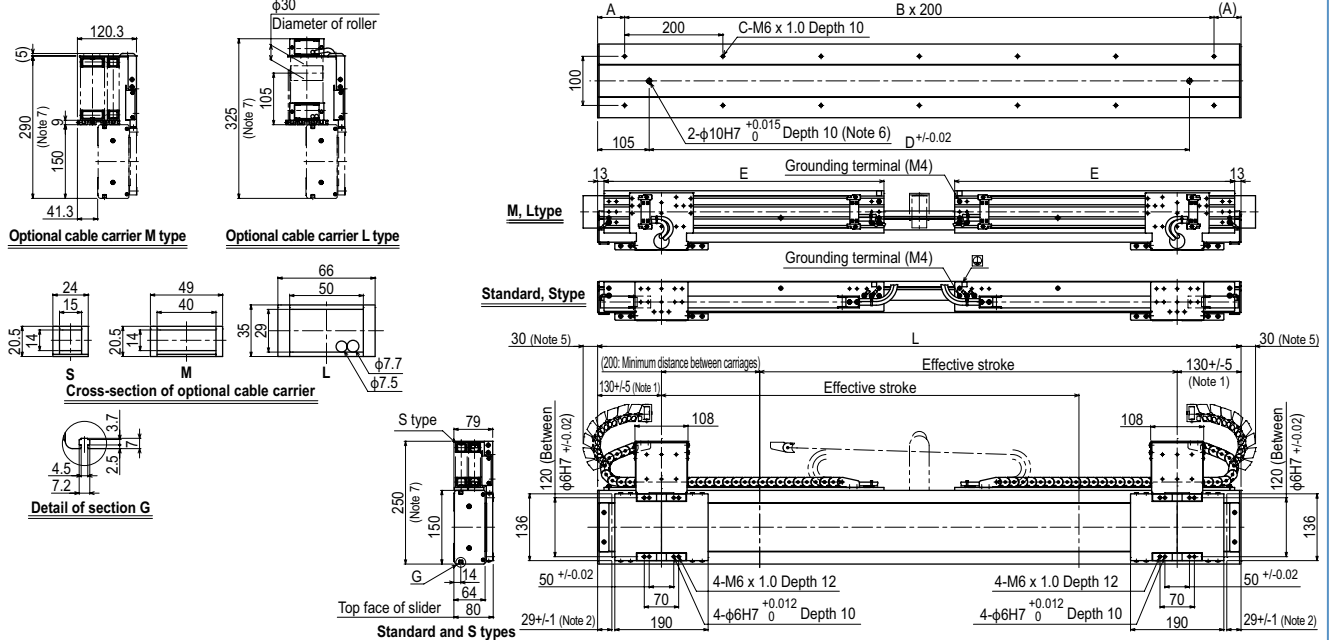
MF20D double carriage horizontal mount model H



Note 1. Position of table carriage when returned to the origin.
Note 2. Stop positions are determined by the mechanical stoppers at both ends.
Note 3. For models with a 2,050mm or longer stroke, optional L type cable carriers can only be used.
Note 4. For models with a 3,050mm or longer stroke and an optional L type cable carrier, a roller is installed to prevent the cable carrier from sagging.
Note 5. Protrusion is the distance the cable carrier extends from the edge of unit when an optional L type cable carrier is used.
Note 6. When using $\phi 10$ H7 hole, do not insert the pin more than the depth stated in the drawing. Otherwise, the motor may break.
Note 7. Depending on the stroke and the operating conditions, the cable carrier bending radius might be larger, making it higher than the dimensions shown in the diagram.

Effective stroke	150	250	350	450	550	650	750	850	950	1050	1150	1250	1350	1450	1550	1650	1750	1850	1950	2050	2150	2250	2350	2450	2550	2650	2750	2850	2950	3050	3150	3250	3350	3450	3550	3650	3750	3850		
L	610	710	810	910	1010	1110	1210	1310	1410	1510	1610	1710	1810	1910	2010	2110	2210	2310	2410	2510	2610	2710	2810	2910	3010	3110	3210	3310	3410	3510	3610	3710	3810	3910	4010	4110	4210	4310		
A	105	55	105	55	105	55	105	55	105	55	105	55	105	55	105	55	105	55	105	55	105	55	105	55	105	55	105	55	105	55	105	55	105	55	105	55	105	55	105	55
B	2	3	3	4	4	5	5	6	6	7	7	8	8	9	9	10	10	11	11	12	12	13	13	14	14	15	15	16	16	17	17	18	18	19	19	20	20	21	21	
C	6	8	8	10	10	12	12	14	14	16	16	18	18	20	20	22	22	24	24	26	26	28	28	30	30	32	32	34	34	36	36	38	38	40	40	42	42	44	44	
D	400	500	600	700	800	900	1000	1100	1200	1300	1400	1500	1600	1700	1800	1900	2000	2100	2200	2300	2400	2500	2600	2700	2800	2900	3000	3100	3200	3300	3400	3500	3600	3700	3800	3900	4000	4100		
Weight (kg)	14.9	16.6	18.3	20.0	21.7	23.5	25.2	26.9	28.6	30.3	32.0	33.7	35.4	37.1	38.8	40.5	42.2	43.9	45.6	47.3	49.0	50.7	52.4	54.1	55.8	57.5	59.2	60.9	62.6	64.3	66.0	67.7	69.4	71.1	72.8	74.5	76.2	77.9		

MF20D double carriage wall mount model W



Note 1. Position of table carriage when returned to the origin.
Note 2. Stop positions are determined by the mechanical stoppers at both ends.
Note 3. For models with a 2,050mm or longer stroke, optional L type cable carriers can only be used.
Note 4. For models with a 3,050mm or longer stroke and an optional L type cable carrier, a roller is installed to prevent the cable carrier from sagging.
Note 5. Protrusion is the distance the cable carrier extends from the edge of unit when an optional L type cable carrier is used.
Note 6. When using $\phi 10$ H7 hole, do not insert the pin more than the depth stated in the drawing. Otherwise, the motor may break.
Note 7. Depending on the stroke and the operating conditions, the cable carrier bending radius might be larger, making it higher than the dimensions shown in the diagram.

Effective stroke	150	250	350	450	550	650	750	850	950	1050	1150	1250	1350	1450	1550	1650	1750	1850	1950	2050	2150	2250	2350	2450	2550	2650	2750	2850	2950	3050	3150	3250	3350	3450	3550	3650	3750	3850		
L	610	710	810	910	1010	1110	1210	1310	1410	1510	1610	1710	1810	1910	2010	2110	2210	2310	2410	2510	2610	2710	2810	2910	3010	3110	3210	3310	3410	3510	3610	3710	3810	3910	4010	4110	4210	4310		
A	105	55	105	55	105	55	105	55	105	55	105	55	105	55	105	55	105	55	105	55	105	55	105	55	105	55	105	55	105	55	105	55	105	55	105	55	105	55	105	55
B	2	3	3	4	4	5	5	6	6	7	7	8	8	9	9	10	10	11	11	12	12	13	13	14	14	15	15	16	16	17	17	18	18	19	19	20	20	21	21	
C	6	8	8	10	10	12	12	14	14	16	16	18	18	20	20	22	22	24	24	26	26	28	28	30	30	32	32	34	34	36	36	38	38	40	40	42	42	44	44	
D	400	500	600	700	800	900	1000	1100	1200	1300	1400	1500	1600	1700	1800	1900	2000	2100	2200	2300	2400	2500	2600	2700	2800	2900	3000	3100	3200	3300	3400	3500	3600	3700	3800	3900	4000	4100		
E	220	270	320	370	420	470	520	570	620	670	720	770	820	870	920	970	1020	1070	1120	1170	1220	1270	1320	1370	1420	1470	1520	1570	1620	1670	1720	1770	1820	1870	1920	1970	2020	2070		
Weight (kg)	14.9	16.6	18.3	20.0	21.7	23.5	25.2	26.9	28.6	30.3	32.0	33.7	35.4	37.1	38.8	40.5	42.2	43.9	45.6	47.3	49.0	50.7	52.4	54.1	55.8	57.5	59.2	60.9	62.6	64.3	66.0	67.7	69.4	71.1	72.8	74.5	76.2	77.9		

MF30/MF30D

Can be used for wall-mount



Ordering method

Single carriage model

MF30

Model MF30: Incremental MF30A: Semi-absolute ^{Note 1}	Cable carrier entry location RH: Horizontal, right LH: Horizontal, left RW: Wall mount, right LW: Wall mount, left	Optional cable carrier for users^{Note 2} No entry: None S: S type M: M type L: L type	Origin position change No entry: L side (Standard) Z: R side No entry: R side (Standard) Z: L side	Grease type No entry: Standard GC: Clean	Stroke 100 to 4000 (100mm pitch)	Cable length 3L: 3.5m 5L: 5m 10L: 10m 3K/5K/10K (Flexible cable) ^{Note 4}
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TSP 220 R

Positioner TS-P ^{Note 5}	Driver: Power-supply voltage / Power capacity 220: 200V/400 to 600W	Regenerative unit R: With RGT	LCD monitor No entry: None L: With LCD	I/O selection NP: NPN PN: PNP CC: CC-Link DN: DeviceNet™ EP: EtherNet/IP™ GW: No I/O board ^{Note 6}
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- Note 1. For the details of the semi-absolute model, please refer to P.33. RDV-P has an incremental model only.
- Note 2. For models with a stroke of 2100 or longer (2050 or longer for double carriage models), only the optional L type cable carriers can be used.
- Note 3. The robot cable is standard cable (3L/5L/10L), but can be changed to flexible cable. See P.594 for details on robot cable.
- Note 4. If a flexible cable is needed for the SR1-P, TS-P, or RDV-P, then select 3K/5K/10K. On the RCX221HP, the standard cable is a flexible cable, so enter 3L/5L/10L when ordering.
- Note 5. These controllers can be mounted on DIN rails. See P.498 for details.
- Note 6. Select this selection when using the gateway function. For details, see P.60.
- Note. It is possible to provide the model without a cable carrier. To find information on wiring (cable terminals) within the cable carrier see P.602.

Double carriage model

MF30D

Model MF30D: Incremental MF30AD: Semi-absolute ^{Note 1}	Installing direction H: Horizontal installation W: Wall mount installation	Optional cable carrier for users^{Note 2} No entry: None S: S type M: M type L: L type	Grease type No entry: Standard GC: Clean	Stroke 150 to 3750 (100mm pitch)	Cable length 3L: 3.5m 5L: 5m 10L: 10m 3K/5K/10K (Flexible cable) ^{Note 4}
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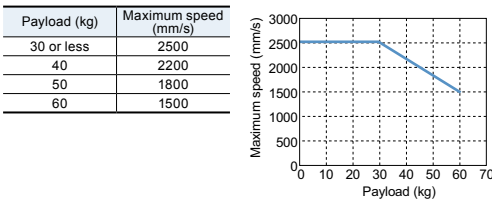
RCX221HP R

Controller RCX221HP SR1-P (2 units) TS-P (2 units) RDV-P (2 units)	Usable for CE No entry: Standard E: CE marking	Regenerative unit R: RG2 (RCX221HP)	I/O selection 1 N: NPN P: PNP CC: CC-Link DN: DeviceNet™ PB: PROFIBUS EN: Ethernet	I/O selection 2 No entry: None NP: OPDIO24/16 (NPN) P: OPDIO24/17 (PNP) EN: Ethernet
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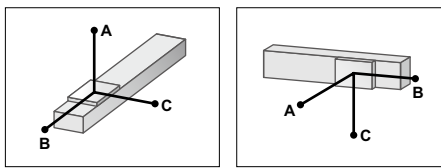
Specifications

Model	MF30	MF30D
Driving method	Steel cored linear motor with falt magnet	
Repeatability (μm)	+/-5	
Scale (μm)	Magnetic type: resolution of 1	
Maximum speed^{Note 2} (mm/sec)	2500	
Rated thrust (N)	125	
Maximum payload^{Note 1} (kg)	60	
Stroke (mm)	100 to 4000 (100mm pitch)	150 to 3750 (100mm pitch)
Linear guide	4 rows of circular arc grooves x 2 rail	
Maximum cross-section outside dimensions (mm)	W150 x H80 (except the cable carrier section)	
Total length (mm)	Stroke+310	Stroke+560
Cable length (m)	Standard: 3.5 / Option: 5,10	

- Note. A vertical model (with brake) is not available with the PHASER series.
- Note. The basic specifications of semi-absolute model are the same as those of the incremental model.
- Note 1. Payload per carrier. When the payload exceeds 30kg, please consult our sales office or sales representative.
- Note 2. Table of maximum speed



Allowable overhang



	Horizontal installation (Unit: mm)			Wall installation (Unit: mm)		
	A	B	C	A	B	C
10kg	3364	2485	1284	1290	1320	2730
20kg	2298	1265	694	650	610	1750
30kg	2060	859	507	430	360	1460
40kg	1570	600	310	205	230	610
50kg	1265	400	180	145	175	470
60kg	1070	350	135	105	140	380

Note. Distance from center of slider top to center of gravity of object being carried at a guide service life of 10,000 km.

Static loading moment

MY	MP	MR
373	373	328

(Unit: N·m)

Controller

Controller	Operating method
SR1-P20-R	Programming / I/O point trace / Remote command / Operation using RS-232C communication
RCX221HP-R RCX240/340	I/O point trace / Remote command
TS-P220-R	Pulse train control
RDV-P220-RBR1	

Cable carrier entry location

RH Horizontal, right	LH Horizontal, left
RW Wall mounted, right	LW Wall mounted, left

Note. Be sure to install in the direction as specified (in cable carrier take-out direction drawing and various specification drawings) individually. Installation in any other way will cause a failure. For requirement of installation in any way other than the above standard installation, please consult YAMAHA as special arrangement will be available.

Optional cable carrier for users

S type	M type	L type
---------------	---------------	---------------

Cable and air tube guide

S: φ8 flexible cable x 1, φ4 air tube x 1
M: φ8 flexible cable x 2, φ6 air tube x 2
L: φ8 flexible cable x 2, φ8 air tube x 3

Space for optional cable for users

Articulated robots
YA

Linear conveyor modules
LCM100

Compact single-axis robots
TRANSEVO

Single-axis robots
FLIP-X

Linear motor single-axis robots
PHASER

Cartesian robots
XX-X

SCARA robots
YK-X

Pick & place robots
YP-X

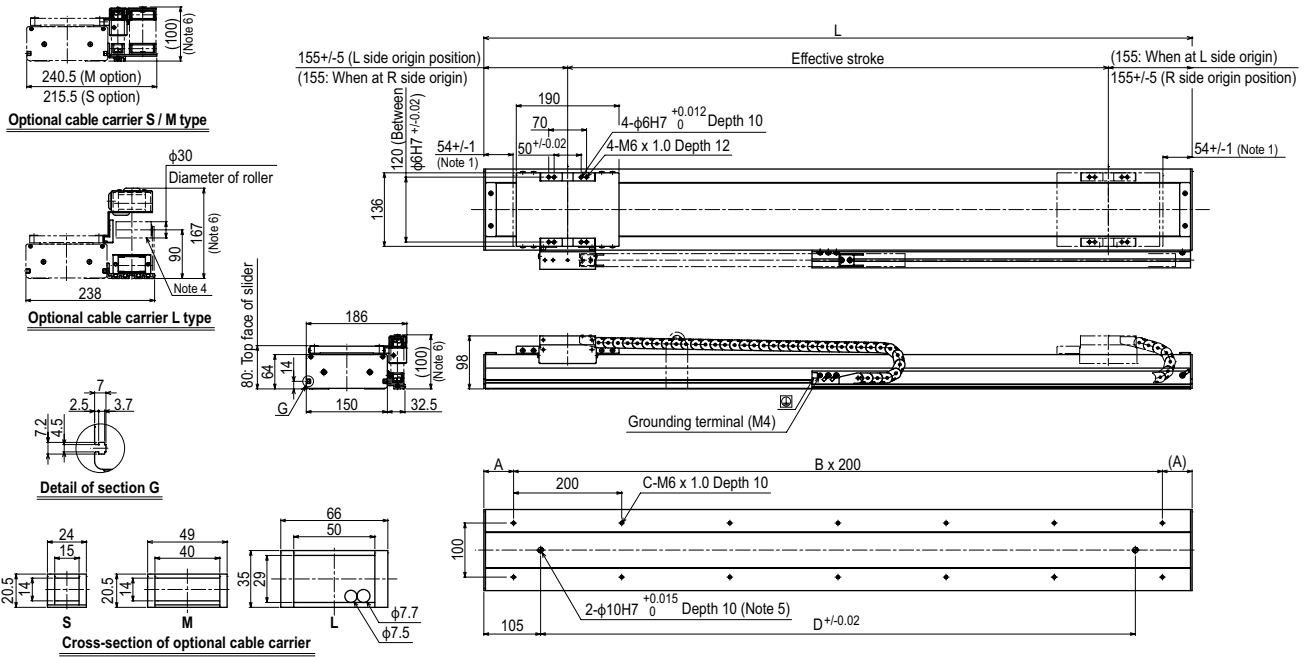
CLEAN

CONTROLLER INFORMATION

MF type

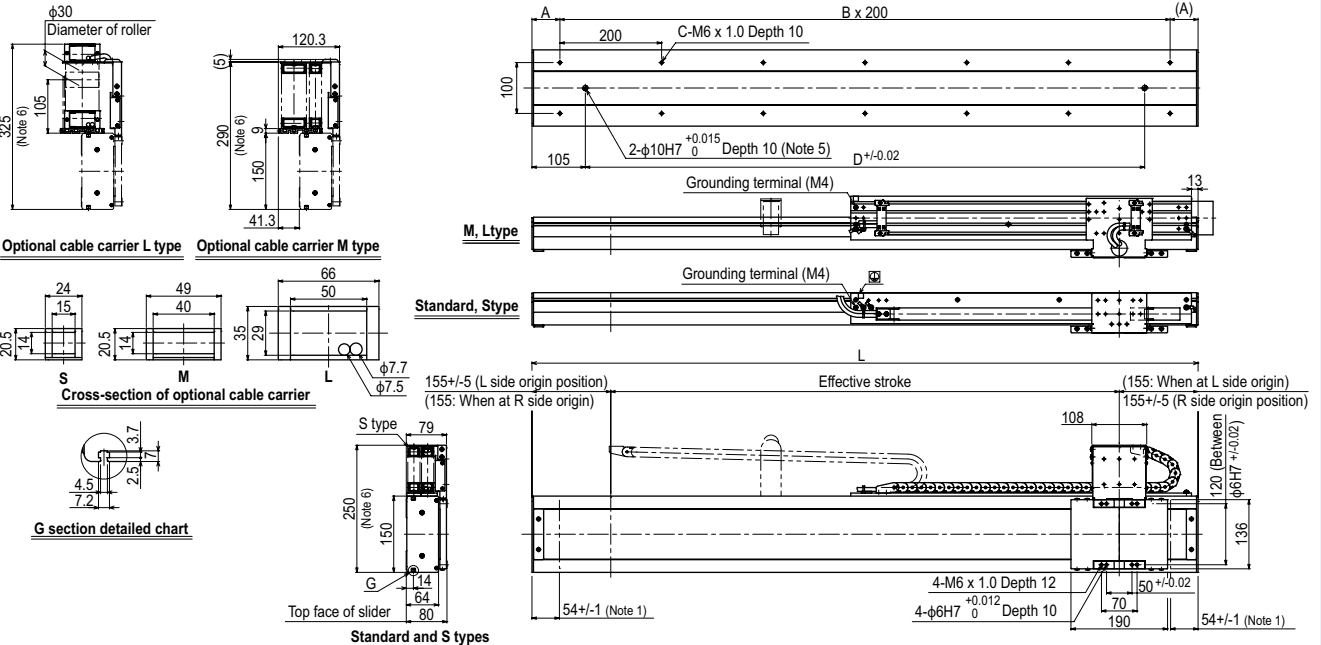
MR type

MF30 single carriage horizontal mount model RH



Note 1. Stop positions are determined by the mechanical stoppers at both ends.
 Note 2. The origin is set on the L side at the time of shipment. It can be changed to the R side by parameter setting.
 Note 3. For models with a 2,100mm or longer stroke, optional L type cable carriers can only be used.
 Note 4. For models with a 3,000mm or longer stroke and an optional L type cable carrier, a roller is installed to prevent the cable carrier from sagging.
 Note 5. When using $\phi 10$ H7 hole, do not insert the pin more than the depth stated in the drawing. Otherwise, the motor may break.
 Note 6. Depending on the stroke and the operating conditions, the cable carrier bending radius might be larger, making it higher than the dimensions shown in the diagram.

MF30 single carriage wall mount model RW



Note 1. Stop positions are determined by the mechanical stoppers at both ends.
 Note 2. The origin is set on the R side at the time of shipment. It can be changed to the L side by parameter setting.
 Note 3. For models with a 2,100mm or longer stroke, optional L type cable carriers can only be used.
 Note 4. For models with a 3,000mm or longer stroke and an optional L type cable carrier, a roller is installed to prevent the cable carrier from sagging.
 Note 5. When using $\phi 10$ H7 hole, do not insert the pin more than the depth stated in the drawing. Otherwise, the motor may break.
 Note 6. Depending on the stroke and the operating conditions, the cable carrier bending radius might be larger, making it higher than the dimensions shown in the diagram.

MF30D double carriage horizontal mount model **H**

Optional cable carrier S / M type
240.5 (M option)
215.5 (S option)

Optional cable carrier L type
φ30 Diameter of roller
167 (Note 6)
90
238
Note 4

Detail of section G
7.2
4.5
2.5
3.7

Cross-section of optional cable carrier
S M L
24 15 49 40 66 50
14 20.5 14 35 29 7.7 7.5

Effective stroke L
155+/-5 (Note 1) 190 4-φ6H7 ^{+0.012}/₀ Depth 10 4-φ6H7 ^{+0.012}/₀ Depth 10 190 155+/-5 (Note 1)
54+/-1 (Note 2) 120 (Between φ6H7 +0.02) 136 50 +/-0.02 70 4-M6 x 1.0 Depth 12 4-M6 x 1.0 Depth 12 70 50 +/-0.02 54+/-1 (Note 2) 120 (Between φ6H7 +0.02)

Grounding terminal (M4)

Notes:
Note 1. Position of table carriage when returned to the origin.
Note 2. Stop positions are determined by the mechanical stoppers at both ends.
Note 3. For models with a 2,050mm or longer stroke, optional L type cable carriers can only be used.
Note 4. For models with a 3,050mm or longer stroke and an optional L type cable carrier, a roller is installed to prevent the cable carrier from sagging.
Note 5. When using φ10 H7 hole, do not insert the pin more than the depth stated in the drawing. Otherwise, the motor may break.
Note 6. Depending on the stroke and the operating conditions, the cable carrier bending radius might be larger, making it higher than the dimensions shown in the diagram.

Effective stroke	150	250	350	450	550	650	750	850	950	1050	1150	1250	1350	1450	1550	1650	1750	1850	1950	2050	2150	2250	2350	2450	2550	2650	2750	2850	2950	3050	3150	3250	3350	3450	3550	3650	3750		
L	710	810	910	1010	1110	1210	1310	1410	1510	1610	1710	1810	1910	2010	2110	2210	2310	2410	2510	2610	2710	2810	2910	3010	3110	3210	3310	3410	3510	3610	3710	3810	3910	4010	4110	4210	4310		
A	55	105	55	105	55	105	55	105	55	105	55	105	55	105	55	105	55	105	55	105	55	105	55	105	55	105	55	105	55	105	55	105	55	105	55	105	55	105	55
B	3	3	4	4	5	5	6	6	7	7	8	8	9	9	10	10	11	11	12	12	13	13	14	14	15	15	16	16	17	17	18	18	19	19	20	20	21	21	
C	8	8	10	10	12	12	14	14	16	16	18	18	20	20	22	22	24	24	26	26	28	28	30	30	32	32	34	34	36	36	38	38	40	40	42	42	44	44	
D	500	600	700	800	900	1000	1100	1200	1300	1400	1500	1600	1700	1800	1900	2000	2100	2200	2300	2400	2500	2600	2700	2800	2900	3000	3100	3200	3300	3400	3500	3600	3700	3800	3900	4000	4100	4200	
Weight (kg)	17.6	19.3	21.0	22.2	24.2	25.6	27.7	29.9	32.6	33.3	33.3	33.4	33.6	33.8	33.9	34.1	34.3	34.5	34.6	34.8	35.0	35.1	35.3	35.5	35.7	35.9	36.1	36.3	36.5	36.7	36.9	37.1	37.2	37.4	37.5	37.7	37.9	38.1	

MF30D double carriage wall mount model **W**

Optional cable carrier L type
φ30 Diameter of roller
325 (Note 6)
105
290 (Note 6)
180
41.3

Optional cable carrier M type
120.3
9
290 (Note 6)
180
41.3

M and L types

Standard and S types

Cross-section of optional cable carrier
S M L
24 15 49 40 66 50
14 20.5 14 35 29 7.7 7.5

Detail of section G
4.5
2.5
3.7
7.2

Standard and S types
S type 79
250 (Note 6)
150
14
80
Top face of slider

Effective stroke L
(250: Minimum distance between carriages)
155+/-5 (Note 1) 108 Effective stroke 108 155+/-5 (Note 1)
120 (Between φ6H7 +0.02) 136 50 +/-0.02 70 4-φ6H7 ^{+0.012}/₀ Depth 10 4-M6 x 1.0 Depth 12 4-M6 x 1.0 Depth 12 70 50 +/-0.02 54+/-1 (Note 2) 120 (Between φ6H7 +0.02)

Notes:
Note 1. Position of table carriage when returned to the origin.
Note 2. Stop positions are determined by the mechanical stoppers at both ends.
Note 3. For models with a 2,050mm or longer stroke, optional L type cable carriers can only be used.
Note 4. For models with a 3,050mm or longer stroke and an optional L type cable carrier, a roller is installed to prevent the cable carrier from sagging.
Note 5. When using φ10 H7 hole, do not insert the pin more than the depth stated in the drawing. Otherwise, the motor may break.
Note 6. Depending on the stroke and the operating conditions, the cable carrier bending radius might be larger, making it higher than the dimensions shown in the diagram.

Effective stroke	150	250	350	450	550	650	750	850	950	1050	1150	1250	1350	1450	1550	1650	1750	1850	1950	2050	2150	2250	2350	2450	2550	2650	2750	2850	2950	3050	3150	3250	3350	3450	3550	3650	3750		
L	710	810	910	1010	1110	1210	1310	1410	1510	1610	1710	1810	1910	2010	2110	2210	2310	2410	2510	2610	2710	2810	2910	3010	3110	3210	3310	3410	3510	3610	3710	3810	3910	4010	4110	4210	4310		
A	55	105	55	105	55	105	55	105	55	105	55	105	55	105	55	105	55	105	55	105	55	105	55	105	55	105	55	105	55	105	55	105	55	105	55	105	55	105	55
B	3	3	4	4	5	5	6	6	7	7	8	8	9	9	10	10	11	11	12	12	13	13	14	14	15	15	16	16	17	17	18	18	19	19	20	20	21	21	
C	8	8	10	10	12	12	14	14	16	16	18	18	20	20	22	22	24	24	26	26	28	28	30	30	32	32	34	34	36	36	38	38	40	40	42	42	44	44	
D	500	600	700	800	900	1000	1100	1200	1300	1400	1500	1600	1700	1800	1900	2000	2100	2200	2300	2400	2500	2600	2700	2800	2900	3000	3100	3200	3300	3400	3500	3600	3700	3800	3900	4000	4100	4200	
E	220	270	320	370	420	470	520	570	620	670	720	770	820	870	920	970	1020	1070	1120	1170	1220	1270	1320	1370	1420	1470	1520	1570	1620	1670	1720	1770	1820	1870	1920	1970	2020		
Weight (kg)	17.6	19.3	21.0	22.2	24.2	25.6	27.7	29.9	32.6	33.3	33.3	33.4	33.6	33.8	33.9	34.1	34.3	34.5	34.6	34.8	35.0	35.1	35.3	35.5	35.7	35.9	36.1	36.3	36.5	36.7	36.9	37.1	37.2	37.4	37.5	37.7	37.9	38.1	

MF75/MF75D



Ordering method

Single carriage model

MF75

Model MF75: Incremental MF75A: Semi-absolute ^{Note 1}	Cable carrier entry location RH: Horizontal, right LH: Horizontal, left	Origin position change No entry: L side (Standard) Z: R side	Grease type No entry: Standard GC: Clean	Stroke 1000 to 4000 (100mm pitch)	Cable length ^{Note 2} 3L: 3.5m 5L: 5m 10L: 10m 3K/5K/10K (Flexible cable) ^{Note 3}
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- Note 1. For the details of the semi-absolute model, please refer to P.33. RDV-P has an incremental model only.
- Note 2. The robot cable is standard cable (3L/5L/10L), but can be changed to flexible cable. See P.594 for details on robot cable.
- Note 3. If a flexible cable is needed for the SR1-P, TS-P, or RDV-P, then select 3K/5K/10K. On the RCX221HP, the standard cable is a flexible cable, so enter 3L/5L/10L when ordering.
- Note 4. These controllers can be mounted on DIN rails. See P.498 for details.
- Note 5. Select this selection when using the gateway function. For details, see P.60.
- Note. It is possible to provide the model without a cable carrier. To find information on wiring (cable terminals) within the cable carrier see P.602.

TSP Positioner ^{Note 4} TS-P	220 Driver: Power-supply voltage / Power capacity 220: 200V/400 to 600W	R Regenerative unit R: With RGU-2	LCD monitor No entry: None L: With LCD	I/O selection NP: NPN PN: PNP CC: CC-Link DN: DeviceNet™ EP: EtherNet/IP™ GW: No I/O board ^{Note 5}
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SR1-P Controller	20 Driver: Power capacity 20: 400 to 600W	Usable for CE No entry: Standard E: CE marking	R Regenerative unit R: With RGU-2	I/O selection N: NPN P: PNP CC: CC-Link DN: DeviceNet™ PB: PROFIBUS
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RDV-P Driver	2 Power-supply voltage 2: AC200V	25 Driver: Power capacity 25: 750W or less	RBR2 Regenerative unit
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Double carriage model

MF75D Model MF75D: Incremental MF75AD: Semi-absolute ^{Note 1}	H Installing direction H: Horizontal installation	Grease type No entry: Standard GC: Clean	Stroke 680 to 3680 (100mm pitch)	Cable length 3L: 3.5m 5L: 5m 10L: 10m 3K/5K/10K (Flexible cable) ^{Note 3}	RCX221HP Controller RCX221HP SR1-P (2 units) TS-P (2 units) RDV-P (2 units)	Usable for CE No entry: Standard E: CE marking	R Regenerative unit	I/O selection 1 N: NPN P: PNP CC: CC-Link DN: DeviceNet™ PB: PROFIBUS EN: Ethernet	I/O selection 2 No entry: None NT: OP-DIO24/16 (NPN) PT: OP-DIO24/17 (PNP) EN: Ethernet
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Specifications

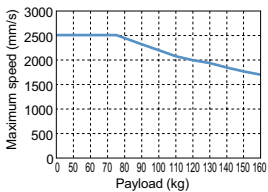
Model	MF75	MF75D
Driving method	Steel cored linear motor with falt magnet	
Repeatability (µm)	+/-5	
Scale (µm)	Magnetic type: resolution of 1	
Maximum speed^{Note 2} (mm/sec)	2500	
Rated thrust (N)	260	
Maximum payload^{Note 1} (kg)	160	
Stroke (mm)	1000 to 4000 (100mm pitch)	680 to 3680 (100mm pitch)
Linear guide	4 rows of circular arc grooves x 2 rail	
Maximum cross-section outside dimensions (mm)	W210xH100 (except the cable carrier section)	
Total length (mm)	Stroke+360	Stroke+680
Cable length (m)	Standard: 3.5 / Option: 5,10	

Note. A vertical model (with brake) is not available with the PHASER series.
Note. The basic specifications of semi-absolute model are the same as those of the incremental model.

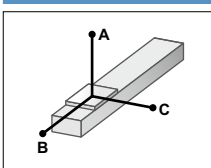
Note 1. Payload per carrier. When the payload exceeds 75kg, please consult our sales office or sales representative.

Note 2. Table of maximum speed

Payload (kg)	Maximum speed (mm/s)
75 or less	2500
90	2310
100	2200
110	2090
120	2000
130	1920
140	1840
150	1770
160	1700



Allowable overhang

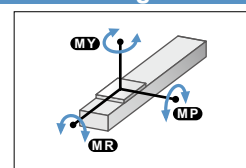


Horizontal installation (Unit: mm)

	A	B	C
20kg	3397	2841	1840
40kg	2795	1389	964
60kg	2200	530	450
80kg	1800	175	150
100kg	1500	130	110
120kg	1250	100	80
140kg	1100	80	65
160kg	950	60	50

Note. Distance from center of slider top to center of gravity of object being carried at a guide service life of 10,000 km.

Static loading moment



(Unit: N-m)

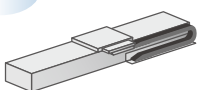
MY	MP	MR
830	831	730

Controller

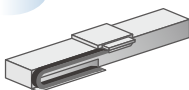
Controller	Operating method
SR1-P20-R (RGU-2)	Programming / I/O point trace /
RCX221HP-R (RG2)	Remote command / Operation using RS-232C communication
TS-P220-R (RGU-2)	I/O point trace / Remote command
RDV-P225-RBR2	Pulse train control

Cable carrier entry location

RH Horizontal, right

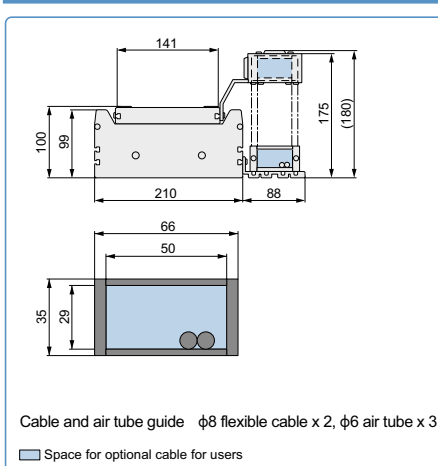


LH Horizontal, left

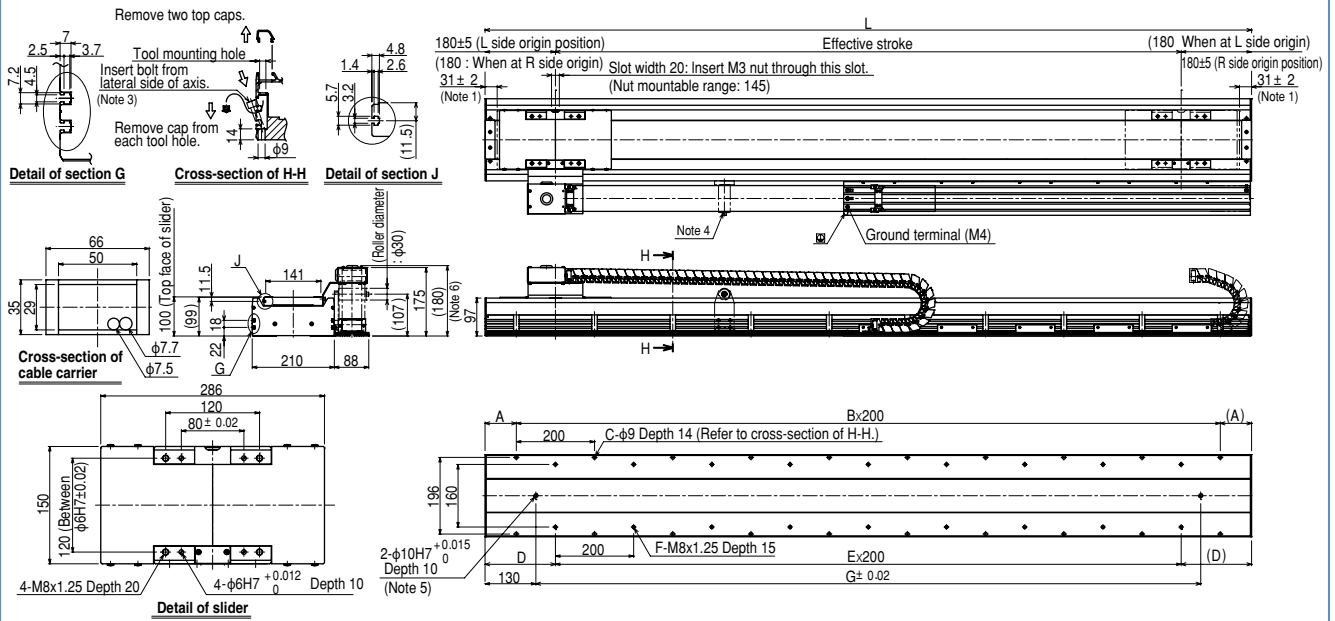


Note. Be sure to install in the direction as specified (in cable carrier take-out direction drawing and various specification drawings) individually. Installation in any other way will cause a failure. For requirement of installation in any way other than the above standard installation, please consult YAMAHA as special arrangement will be available.

Cable carrier



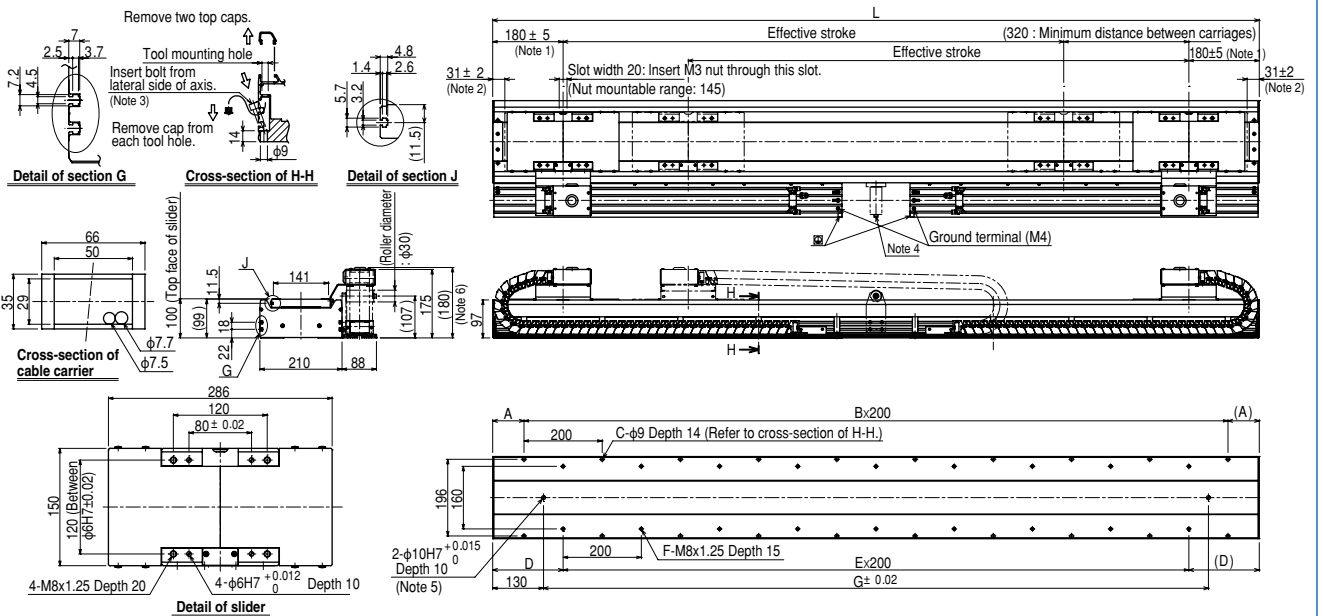
MF75 single carriage horizontal mount model **RH**



Note 1. Stop positions are determined by the mechanical stoppers at both ends.
 Note 2. The origin is set on the L side (as shown above) at the time of shipment. It can be changed to the R side by parameter setting.
 Note 3. The length under head of M8 hex socket head bolts for installing the robot body must not be longer than 30mm.
 Note 4. For models with a 3,000mm or longer stroke, a roller is installed to prevent the cable carrier from sagging.
 Note 5. When using $\phi 10$ H7 hole, do not insert the pin more than the depth stated in the drawing. Otherwise, the motor may break.
 Note 6. Depending on the stroke and the operating conditions, the cable carrier bending radius might be larger, making it higher than the dimensions shown in the diagram.

Effective stroke	1000	1100	1200	1300	1400	1500	1600	1700	1800	1900	2000	2100	2200	2300	2400	2500	2600	2700	2800	2900	3000	3100	3200	3300	3400	3500	3600	3700	3800	3900	4000
L	1360	1460	1560	1660	1760	1860	1960	2060	2160	2260	2360	2460	2560	2660	2760	2860	2960	3060	3160	3260	3360	3460	3560	3660	3760	3860	3960	4060	4160	4260	4360
A	180	230	80	130	180	230	80	130	180	230	80	130	180	230	80	130	180	230	80	130	180	230	80	130	180	230	80	130	180	230	80
B	5	5	7	7	7	7	9	9	9	9	11	11	11	11	13	13	13	13	15	15	15	15	17	17	17	17	19	19	19	19	21
C	12	12	16	16	16	16	20	20	20	24	24	24	24	28	28	28	28	32	32	32	32	32	36	36	36	36	40	40	40	40	44
D	80	130	180	230	80	130	180	230	80	130	180	230	80	130	180	230	80	130	180	230	80	130	180	230	80	130	180	230	80	130	180
E	6	6	6	6	8	8	8	8	10	10	10	10	12	12	12	12	14	14	14	14	16	16	16	16	18	18	18	18	20	20	20
F	14	14	14	14	18	18	18	18	22	22	22	22	26	26	26	26	30	30	30	30	34	34	34	34	38	38	38	38	42	42	42
G	1100	1200	1300	1400	1500	1600	1700	1800	1900	2000	2100	2200	2300	2400	2500	2600	2700	2800	2900	3000	3100	3200	3300	3400	3500	3600	3700	3800	3900	4000	4100
Weight (kg)	46	49	51	54	56	59	61	64	66	69	71	74	76	79	81	84	86	89	91	94	96	99	101	104	106	109	111	114	116	119	121

MF75D double carriage mount model **H**



Note 1. Position of table carriage when returned to the origin.
 Note 2. Stop positions are determined by the mechanical stoppers at both ends.
 Note 3. The length under head of M8 hex socket head bolts for installing the robot body must not be longer than 30mm.
 Note 4. For models with a 3,080mm or longer stroke, a roller is installed to prevent the cable carrier from sagging.
 Note 5. When using $\phi 10$ H7 hole, do not insert the pin more than the depth stated in the drawing. Otherwise, the motor may break.
 Note 6. Depending on the stroke and the operating conditions, the cable carrier bending radius might be larger, making it higher than the dimensions shown in the diagram.

Effective stroke	680	780	880	980	1080	1180	1280	1380	1480	1580	1680	1780	1880	1980	2080	2180	2280	2380	2480	2580	2680	2780	2880	2980	3080	3180	3280	3380	3480	3580	3680
L	1360	1460	1560	1660	1760	1860	1960	2060	2160	2260	2360	2460	2560	2660	2760	2860	2960	3060	3160	3260	3360	3460	3560	3660	3760	3860	3960	4060	4160	4260	4360
A	180	230	80	130	180	230	80	130	180	230	80	130	180	230	80	130	180	230	80	130	180	230	80	130	180	230	80	130	180	230	80
B	5	5	7	7	7	7	9	9	9	9	11	11	11	11	13	13	13	13	15	15	15	15	17	17	17	17	19	19	19	19	21
C	12	12	16	16	16	16	20	20	20	20	24	24	24	24	28	28	28	28	32	32	32	32	32	36	36	36	36	40	40	40	44
D	80	130	180	230	80	130	180	230	80	130	180	230	80	130	180	230	80	130	180	230	80	130	180	230	80	130	180	230	80	130	180
E	6	6	6	6	8	8	8	8	10	10	10	10	12	12	12	12	14	14	14	14	16	16	16	16	18	18	18	18	20	20	20
F	14	14	14	14	18	18	18	18	22	22	22	22	26	26	26	26	30	30	30	30	34	34	34	34	38	38	38	38	42	42	42
G	1100	1200	1300	1400	1500	1600	1700	1800	1900	2000	2100	2200	2300	2400	2500	2600	2700	2800	2900	3000	3100	3200	3300	3400	3500	3600	3700	3800	3900	4000	4100
Weight (kg)	57	60	62	65	67	70	73	75	78	81	83	86	88	91	94	96	99	101	104	107	109	112	114	117	120	122	125	127	130	133	135

Articulated robots
 YA
 Linear conveyor modules
 LCM100
 Compact single-axis robots
 TRANSERVO
 Single-axis robots
 FLIP-X
 Linear motor single-axis robots
 PHASER
 Cartesian robots
 XX-X
 SCARA robots
 YK-X
 Pick & place robots
 YP-X
 CLEAN
 CONTROLLER INFORMATION
 MF type
 MR type

MR12/MR12D

Can be used for wall-mount

Ordering method

Single carriage model

MR12

Model
MR12: Incremental
MR12A: Semi-absolute ^{Note 1}

Cable carrier entry location
RH: Horizontal, right
LH: Horizontal, left
RW: Wall mounted, right
LW: Wall mounted, left

Optional cable carrier for users
No entry: None
S: S type
M: M type

Origin position change
Horizontal
No entry: L side (Standard)
Z: R side
Wall
No entry: R side (Standard)
Z: L side

Grease type
No entry: Standard
GC: Clean

Stroke
50 to 1050 (100mm pitch)

Cable length ^{Note 2}
3L: 3.5m
5L: 5m
10L: 10m
3K/5K/10K (Flexible cable) ^{Note 3}

TSP

Positioner ^{Note 4}
TS-P

Driver: Power-supply voltage / Power capacity
105: 100V/100W or less
205: 200V/100W or less

LCD monitor
No entry: None
L: With LCD

I/O selection
NP: NPN
PN: PNP
CC: CC-Link
DN: DeviceNet™
EP: EtherNet/IP™
GW: No I/O board ^{Note 5}

SR1-P

Controller

Driver: Power capacity
05: 100W or less

Usable for CE
No entry: Standard
E: CE marking

I/O selection
N: NPN
P: PNP
CC: CC-Link
DN: DeviceNet™
PB: PROFIBUS

RDV-P

Driver

Power-supply voltage
2: AC200V

Driver: Power capacity
05: 100W or less

- Note 1. For the details of the semi-absolute model, please refer to P.33. RDV-P has an incremental model only.
- Note 2. The robot cable is standard cable (3L/5L/10L), but can be changed to flexible cable. See P.594 for details on robot cable.
- Note 3. If a flexible cable is needed for the SR1-P, TS-P, or RDV-P, then select 3K/5K/10K. On the RCX221, the standard cable is a flexible cable, so enter 3L/5L/10L when ordering.
- Note 4. These controllers can be mounted on DIN rails. See P.498 for details.
- Note 5. Select this selection when using the gateway function. For details, see P.60.
- Note. It is possible to provide the model without a cable carrier. To find information on wiring (cable terminals) within the cable carrier see P.602.

Double carriage model

MR12D

Model
MR12D: Incremental
MR12AD: Semi-absolute ^{Note 1}

Installing direction
H: Horizontal installation
W: Wall mounted installation

Optional cable carrier for users
No entry: None
S: S type
M: M type

Grease type
No entry: Standard
GC: Clean

Stroke
50 to 1050 (100mm pitch)

Cable length ^{Note 3}
3L: 3.5m
5L: 5m
10L: 10m
3K/5K/10K (Flexible cable) ^{Note 3}

RCX221

Controller
RCX221
SR1-P (2 units)
TS-P (2 units)
RDV-P (2 units)

Usable for CE
No entry: Standard
E: CE marking

I/O selection 1
N: NPN
P: PNP
CC: CC-Link
DN: DeviceNet™
PB: PROFIBUS
EN: Ethernet

I/O selection 2
No entry: None
N1: OP.DIO24/16 (NPN)
P1: OP.DIO24/17 (PNP)
EN: Ethernet

Specifications ^{Note}

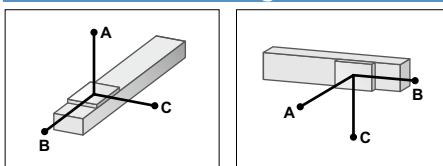
Model	MR12	MR12D
Driving method / Shaft diameter	Shaft motor / $\phi 12$	
Repeatability (μm)	+/-5 or less	
Scale (μm)	Magnetic type: resolution of 1	
Maximum speed ^{Note 1} (mm/sec)	2500	
Rated thrust (N)	18	
Maximum payload ^{Note 2} (kg)	5	
Stroke (mm)	50 to 1050 (50mm pitch)	
Linear guide	4 rows of circular arc grooves \times 2 rail	
Maximum cross-section outside dimensions (mm)	W60 \times H90 (except the cable carrier section)	
Total length (mm)	Stroke+288	Stroke+488
Cable length (m)	Standard: 3.5 / Option: 5, 10	

Note. A vertical model (with brake) is not available with the PHASER series. Note. The basic specifications of semi-absolute model are the same as those of the incremental model.

Note 1. Maximum speed may not be obtained depending on operating conditions.

Note 2. Maximum payload per carriage.

Allowable overhang ^{Note}



Horizontal installation (Unit: mm)

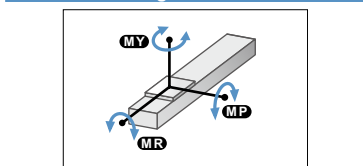
	A	B	C
1kg	600	600	600
2kg	1200	1200	598
3kg	1800	1800	406
5kg	3000	1561	241

Wall installation (Unit: mm)

	A	B	C
1kg	600	600	600
2kg	529	1200	1200
3kg	323	1450	1800
5kg	162	589	3000

Note. Distance from center of slider top to center of gravity of object being carried at a guide service life of 10,000 km.

Static loading moment



(Unit: N·m)

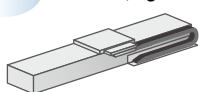
MY	MP	MR
107	107	89

Controller

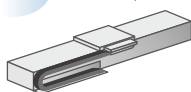
Controller	Operating method
SR1-P05	Programming / I/O point trace / Remote command /
RCX221 RCX240/340	Operation using RS-232C communication
TS-P105	I/O point trace /
TS-P205	Remote command
RDV-P205	Pulse train control

Cable carrier entry location

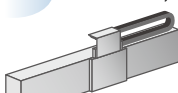
RH Horizontal, right



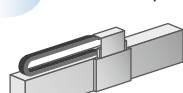
LH Horizontal, left



RW Wall mounted, right



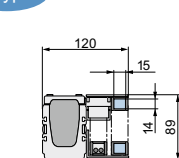
LW Wall mounted, left



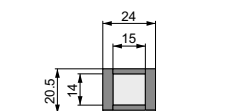
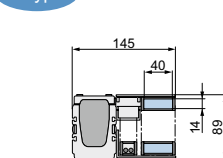
Note. Be sure to install in the direction as specified (in cable carrier take-out direction drawing and various specification drawings) individually. Installation in any other way will cause a failure. For requirement of installation in any way other than the above standard installation, please consult YAMAHA as special arrangement will be available.

Optional cable carrier for users

S type



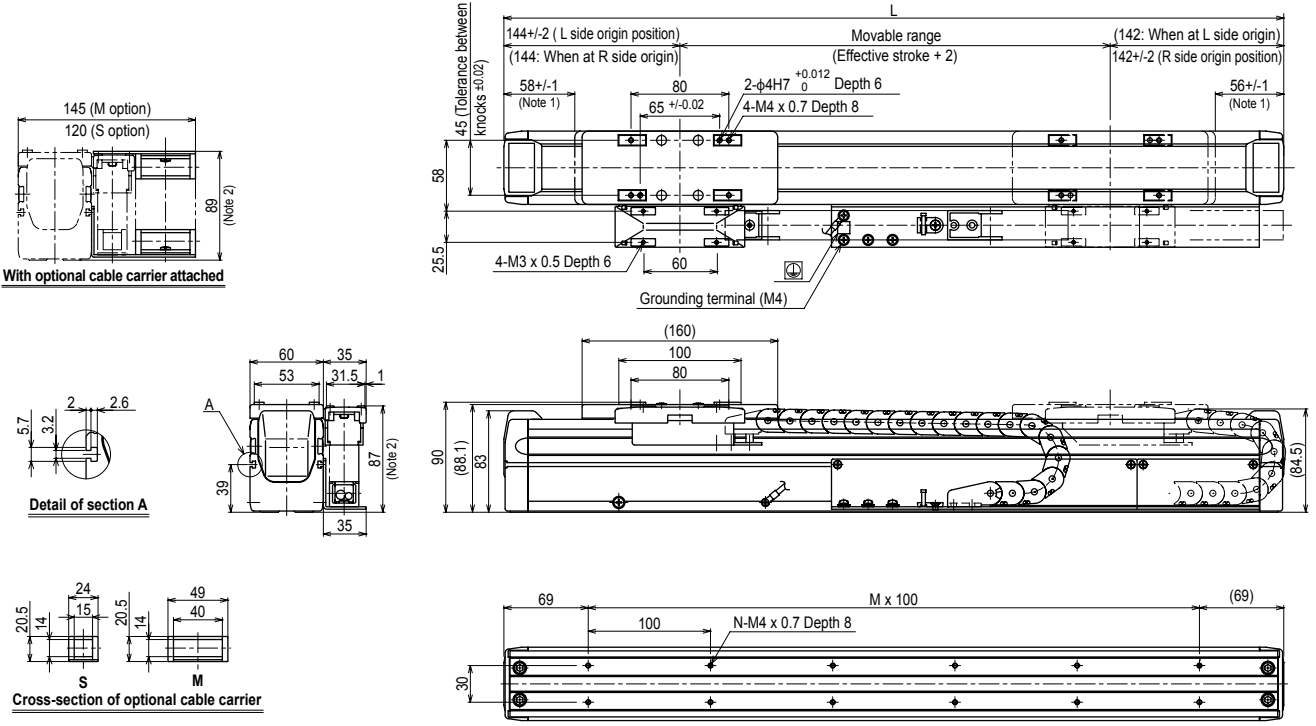
M type



Space for optional cable for users

Note. The cable and air hoses should take up less than 30% of the space when storing them inside the cable carrier. Lay out the cables and air hoses in rows inside the cable carrier so they do not cross each other.

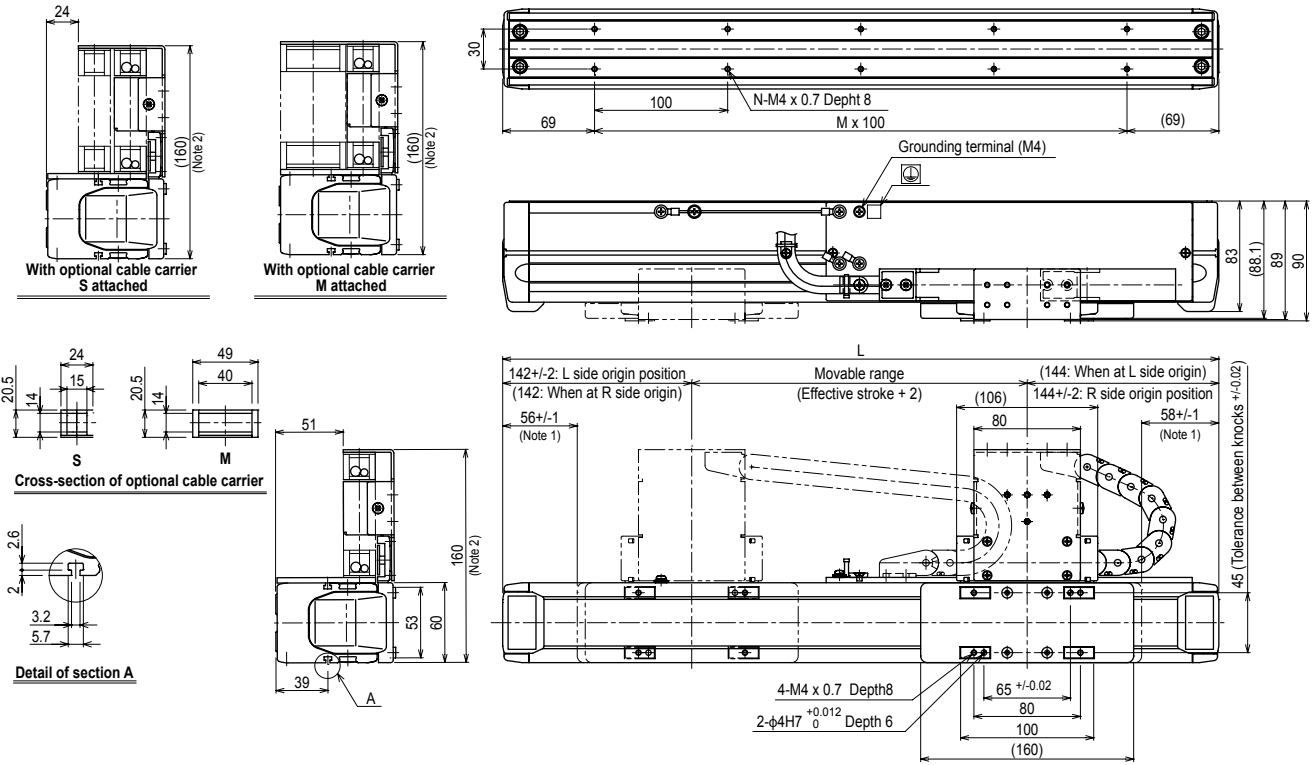
MR12 single carriage horizontal mount model **RH**



Effective stroke	50	150	250	350	450	550	650	750	850	950	1050
L	338	438	538	638	738	838	938	1038	1138	1238	1338
M	2	3	4	5	6	7	8	9	10	11	12
N	6	8	10	12	14	16	18	20	22	24	26
Weight (kg)	3.9	4.4	5.0	5.6	6.1	6.7	7.3	7.9	8.4	9.0	9.5

Note 1. Stop positions are determined by the mechanical stoppers at both ends.
 Note 2. Depending on the stroke and the operating conditions, the cable carrier bending radius might be larger, making it higher than the dimensions shown in the diagram.
 Note. The origin is set on the L side at the time of shipment. It can be changed to the R side by parameter setting.

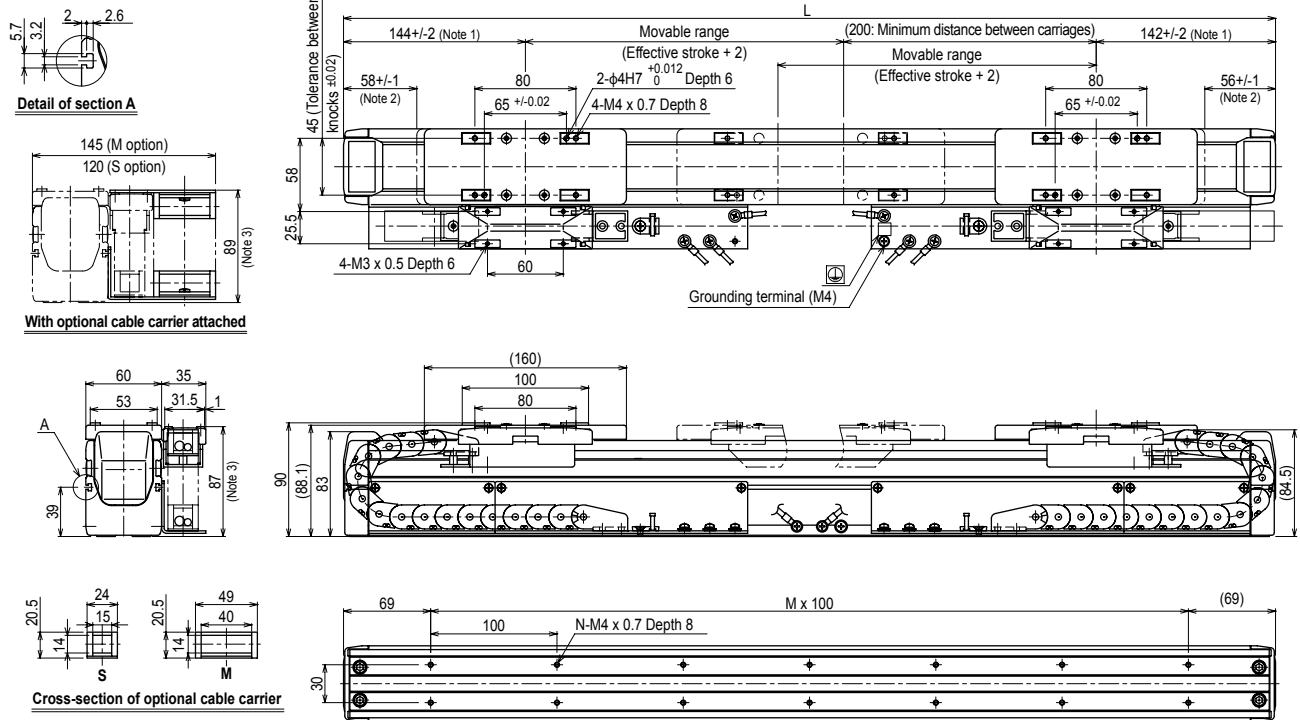
MR12 single carriage wall mount model **RW**



Effective stroke	50	150	250	350	450	550	650	750	850	950	1050
L	338	438	538	638	738	838	938	1038	1138	1238	1338
M	2	3	4	5	6	7	8	9	10	11	12
N	6	8	10	12	14	16	18	20	22	24	26
Weight (kg)	3.9	4.4	5.0	5.6	6.1	6.7	7.3	7.9	8.4	9.0	9.5

Note 1. Stop positions are determined by the mechanical stoppers at both ends.
 Note 2. Depending on the stroke and the operating conditions, the cable carrier bending radius might be larger, making it higher than the dimensions shown in the diagram.
 Note. The origin is set on the R side at the time of shipment. It can be changed to the L side by parameter setting.

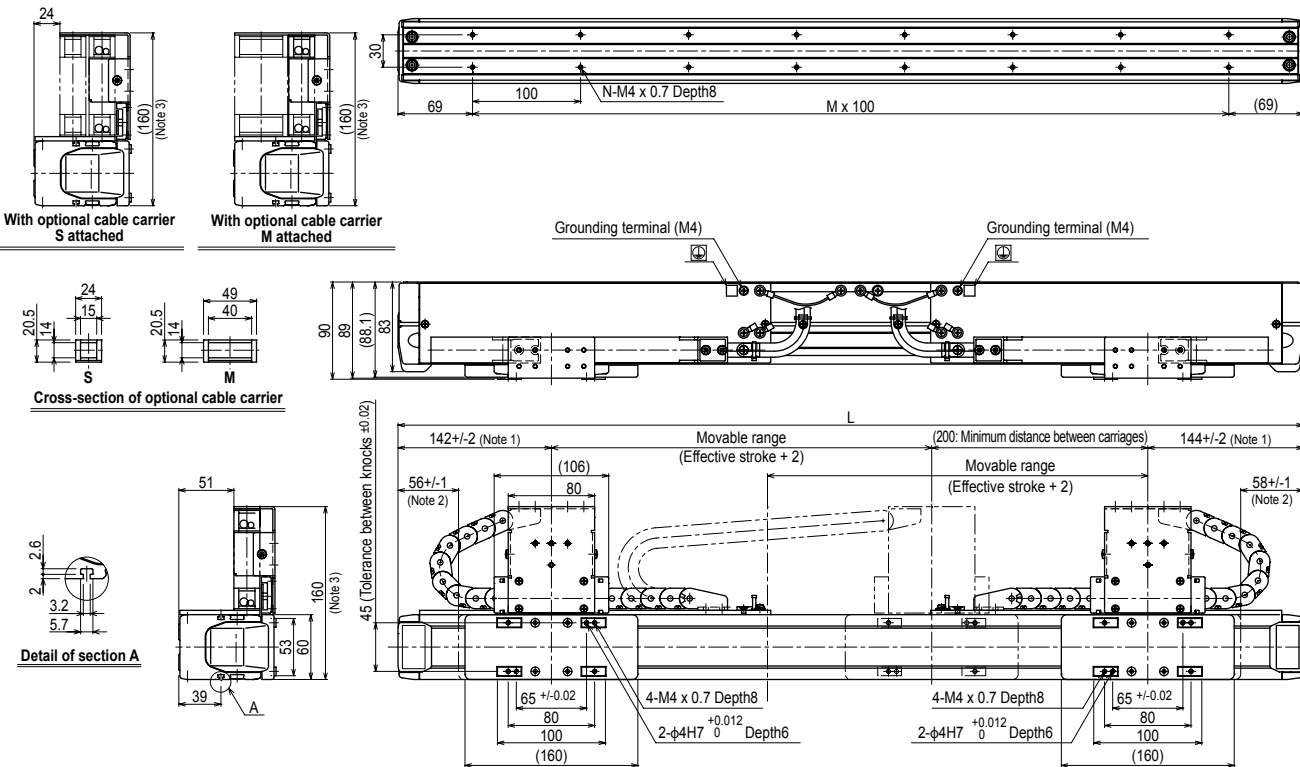
MR12D double carriage horizontal mount model H



Effective stroke	50	150	250	350	450	550	650	750	850	950	1050
L	538	638	738	838	938	1038	1138	1238	1338	1438	1538
M	4	5	6	7	8	9	10	11	12	13	14
N	10	12	14	16	18	20	22	24	26	28	30
Weight (kg)	5.7	6.3	6.8	7.3	8.0	8.6	9.1	9.7	10.2	10.8	11.3

Note 1. Position of the table slider when returned to the origin.
 Note 2. Stop positions are determined by the mechanical stoppers at both ends.
 Note 3. Depending on the stroke and the operating conditions, the cable carrier bending radius might be larger, making it higher than the dimensions shown in the diagram.

MR12D double carriage wall mount model W



Effective stroke	50	150	250	350	450	550	650	750	850	950	1050
L	538	638	738	838	938	1038	1138	1238	1338	1438	1538
M	4	5	6	7	8	9	10	11	12	13	14
N	10	12	14	16	18	20	22	24	26	28	30
Weight (kg)	5.7	6.3	6.8	7.3	8.0	8.6	9.1	9.7	10.2	10.8	11.3

Note 1. Position of the table slider when returned to the origin.
 Note 2. Stop positions are determined by the mechanical stoppers at both ends.
 Note 3. Depending on the stroke and the operating conditions, the cable carrier bending radius might be larger, making it higher than the dimensions shown in the diagram.