

N15



Ordering method

N15-20

Model	Lead designation	Cable carrier entry location	Cable carrier specification	Origin position change	Grease type	Stroke	Cable length
		RH: Horizontal, right LH: Horizontal, left RW: Wall, right LW: Wall, left	S: Standard C: Cable carrier M: Optional C: Cable carrier	Hori- zontal None: R side (Standard) Z: L side Wall None: L side (Standard) Z: R side	None: Standard GC: Clean	500 to 2000 (100mm pitch)	3L: 3.5m 5L: 5m 10L: 10m 3K/5K/10K (Flexible cable)

TSX Positioner	220 Driver: Power-supply voltage / Power capacity 220: 200V/400 to 600W	R Regenerative unit R: With RGT	LCD monitor No entry: None L: With LCD	I/O selection NP: NPN PN: PNP CC: CC-Link DN: DeviceNet™ EP: EtherNet/IP™ PT: PROFINET GW: No I/O board	Battery B: With battery (Absolute) N: None (Incremental)
SR1-X Controller	20 Driver: Power capacity 20: 400 to 600W	Usable for CE No entry: Standard E: CE marking	R Regenerative unit R: With RGT	I/O selection N: NPN P: PNP CC: CC-Link DN: DeviceNet™ PB: PROFIBUS	Battery B: With battery (Absolute) N: None (Incremental)
RDV-X Driver	2 Power-supply voltage 2: AC200V	20 Driver: Power capacity 20: 600W or less	RBR1 Regenerative unit		

Note 1. To find information on cable carrier extraction directions see P.173.
 Note 2. The robot cable is standard cable (3L/5L/10L), but can be changed to flexible cable. See P.594 for details on robot cable.
 Note 3. See P.498 for DIN rail mounting bracket.
 Note 4. Select this selection when using the gateway function. For details, see P.60.

Specifications

AC servo motor output (W)	400
Repeatability (mm)	+/-0.01
Deceleration mechanism	Ball screw φ15 (Class C7)
Ball screw lead (mm)	20
Maximum speed (mm/sec)	1200
Maximum payload (kg)	50
Rated thrust (N)	339
Stroke (mm)	500 to 2000 (100mm pitch)
Overall length (mm)	Stroke+330
Maximum dimensions of cross section of main unit (mm)	W145 × H120
Cable length (m)	Standard: 3.5 / Option: 5.10
Linear guide type	4 rows of circular arc grooves × 2 rail
Position detector	Resolvers
Resolution (Pulse/rotation)	16384

Note 1. Positioning repeatability in one direction.
 Note 2. The maximum speed may not be reached when the moving distance is short.
 Note 3. Position detectors (resolvers) are common to incremental and absolute specifications. If the controller has a backup function then it will be absolute specifications.

Allowable overhang

Horizontal installation (Unit: mm)	Wall installation (Unit: mm)		
	A	B	C
Lead 20	10kg 3048	2322	1259
	30kg 1489	841	500
	50kg 1278	544	344

Note. Distance from center of slider top to center of gravity of object being carried at a guide service life of 10,000 km.

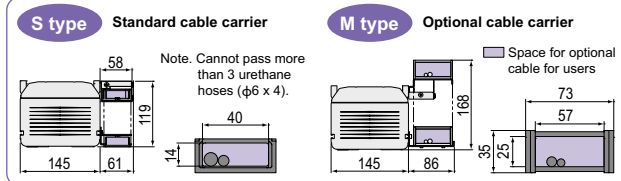
Static loading moment

(Unit: N·m)		
MY	MP	MR
691	692	608

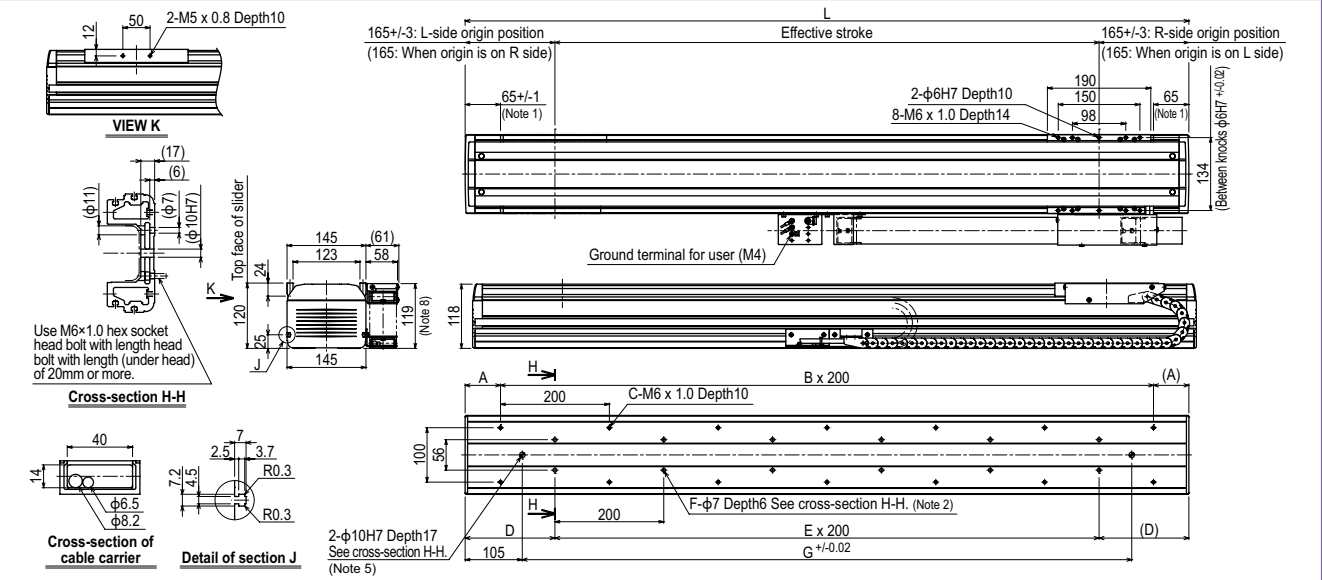
Controller

Controller	Operation method
SR1-X20-R RCX221/222 RCX240/340	Programming / I/O point trace / Remote command / Operation using RS-232C communication
TS-X220-R	I/O point trace / Remote command
RDV-X220-RBR1	Pulse train control

Cable carrier for users



N15: Horizontal installation / Standard Cable carrier specification RH



Note 1. Stop positions are determined by the mechanical stoppers at both ends.
 Note 2. When using φ7 holes for installation, do not use a washer, spring washer, etc. in the main unit.
 Note 3. When shipped from the factory, the horizontal model has the origin on the right side and the wall model has the origin on the left side. (This diagram shows the machine whose cable carrier taken out from right.)
 Note 4. If the model is a standard cable carrier specification, it is not possible to pass 3 or more φ6 × 4 urethane air hoses.
 Note 5. When using a φ10H7 hole, make sure that the pin does not go into deeper than as shown in the drawing.
 Note 6. Contact us for vertical installation.
 Note 7. Weight of models with no brake. The weight of brake-attached models is 1 kg heavier than the models with no brake shown in the table.
 Note 8. Depending on the stroke and the operating conditions, the cable carrier bending radius might be larger, making it higher than the dimensions shown in the diagram.

Effective stroke	500	600	700	800	900	1000	1100	1200	1300	1400	1500	1600	1700	1800	1900	2000
L	830	930	1030	1130	1230	1330	1430	1530	1630	1730	1830	1930	2030	2130	2230	2330
A	15	65	15	65	15	65	15	65	15	65	15	65	15	65	15	65
B	4	4	5	5	6	6	7	7	8	8	9	9	10	10	11	11
C	10	10	12	12	14	14	16	16	18	18	20	20	22	22	24	24
D	115	165	115	165	115	165	115	165	115	165	115	165	115	165	115	165
E	3	3	4	4	5	5	6	6	7	7	8	8	9	9	10	10
F	8	8	10	10	12	12	14	14	16	16	18	18	20	20	22	22
G	620	720	820	920	1020	1120	1220	1320	1420	1520	1620	1720	1820	1920	2020	2120
Weight (kg)	19	20	22	23	24	26	27	29	30	32	33	35	36	38	39	40

Articulated robots
YA

Linear conveyor modules
LCM100

Compact single-axis robots
TRANSEVO

Single-axis robots
FLIP-X

Linear motor single-axis robots
PHASER

Cartesian robots
XX-X

SCARA robots
YK-X

Pick & place robots
YP-X

CLEAN

CONTROLLER INFORMATION

T type

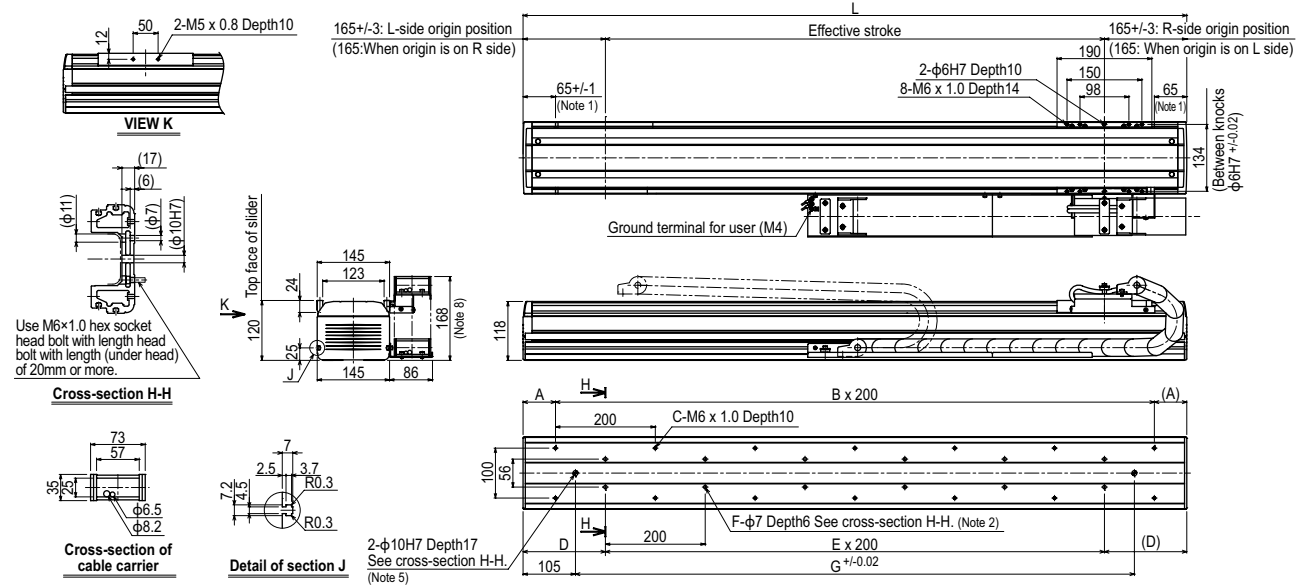
F type

GF type

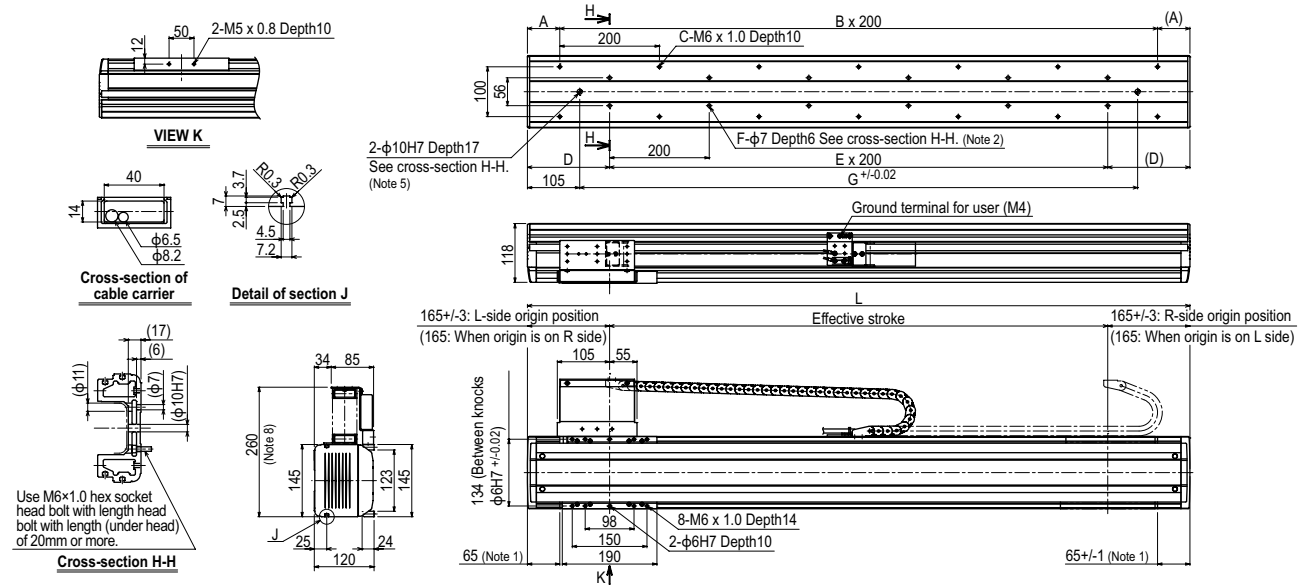
N type

BR type

N15: Horizontal installation / Optional Cable carrier specification **RH**



N15: Wall installation / Standard Cable carrier specification **RW**



N15: Wall installation / Optional Cable carrier specification **RW**

