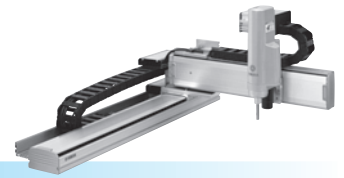


FXYx 3 axes / ZS

- Arm type
- Cable carrier
- Z-axis shaft vertical type



Ordering method

FXYx - C					15		RCX240				BB	
Model	Cable	Combination	X-axis stroke	Y-axis stroke	ZR-axis	Z-axis stroke	Cable length	Controller	Usable for CE	Option I/O <small>Note 1</small>	Network option	Battery
A1 A2 A3 A4			15 to 105cm	15 to 55cm	ZS12 ZS6		3L: 3.5m (Standard) 5L: 5m 10L: 10m		No entry: Standard E: CE marking	N: P: Standard I/O 16/8 N1, P1: 40/24 N2, P2: 64/40 N3, P3: 88/56 N4, P4: 112/72	No entry: None CC: CC-Link DN: DeviceNet PB: Profibus EN: Ethernet YC: YC-Link <small>150-2</small>	BB: 4 pcs

Note 1. N to N4 if NPN was selected, or P to P4 if PNP was selected for the I/O board.
Note 2. Available only for the master.

Specification

	X-axis	Y-axis	Z-axis ZS12	Z-axis ZS6
Axis construction	-	-	-	-
AC servo motor output (W)	100	60	60	60
Repeatability <small>Note 1</small> (mm)	+/-0.01	+/-0.02	+/-0.02	+/-0.02
Drive system	Ball screw (Class C7)	Ball screw (Class C10)	Ball screw (Class C10)	Ball screw (Class C10)
Ball screw lead (Deceleration ratio) (mm)	20	12	12	6
Maximum speed <small>Note 2</small> (mm/sec)	1200	800	1000	500
Moving range (mm)	150 to 1050	150 to 550	150	150
Robot cable length (m)	Standard: 3.5 Option: 5,10			

Note 1. Positioning repeatability in one direction.
Note 2. When the X-axis stroke is longer than 750mm, resonance of the ball screw may occur depending on the operation conditions (critical speed). In this case, reduce the speed setting on the program by referring to the maximum speeds shown in the table below.

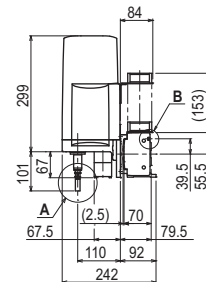
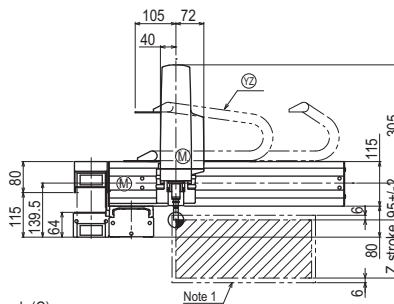
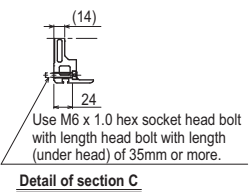
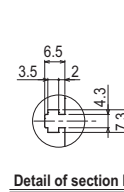
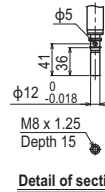
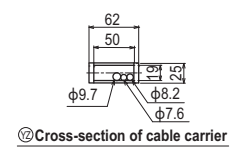
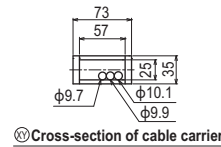
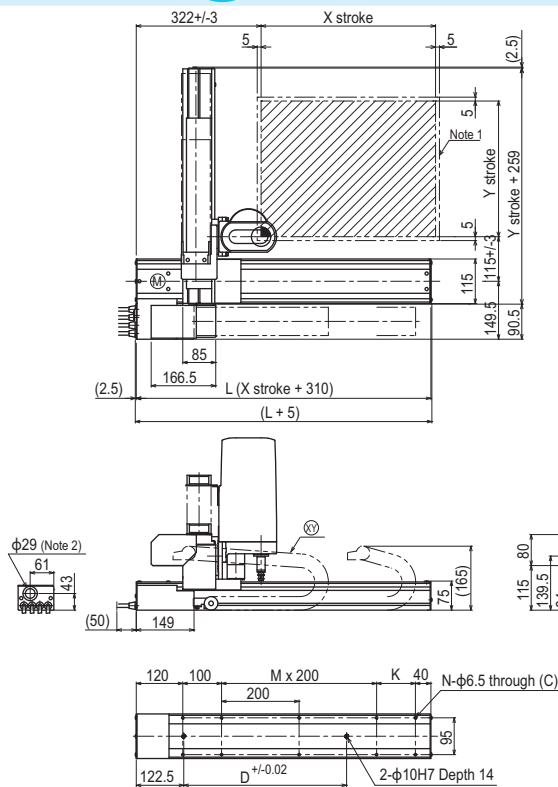
Maximum payload (kg)

Y stroke (mm)	ZS12	ZS6
150	3	5
250	3	5
350	3	5
450	3	5
550	3	3

Controller

Controller	Operation method
RCX240	Programming / I/O point trace / Remote command / Operation using RS-232C communication

FXYx 3 axes / ZS A1



X stroke	150	250	350	450	550	650	750	850	950	1050		
	L	460	560	660	760	860	960	1060	1160	1260	1360	
K	200	100	200	100	200	100	200	100	200	100		
D	240	240	420	420	600	600	780	960	960	1140		
M	0	1	1	2	2	3	3	4	4	5		
N	6	8	8	10	10	12	12	14	14	16		
Y stroke	150	250	350	450	550							
Z stroke	150											
Maximum speed for each stroke (mm/sec) <small>Note 3</small>	X-axis	1200				960	780	600	540			
	Speed setting	-				80%	65%	50%	45%			

Note 1. The moving range when returning to origin and the stop position when stopping by the mechanical stopper.
Note 2. User cable extraction port.

Note 3. When the X-axis stroke is longer than 750mm, resonance of the ball screw may occur depending on the operation conditions (critical speed). In this case, reduce the speed setting on the program by referring to the maximum speeds shown in the table at the left.

APPLICATION
Compact
single-axis robots
TRANSERO

Single-axis robots
FLIP-X

Linear motor
single-axis robots
PHASER

Cartesian
robots
XX-X

SCARA
robots
YK-XG

Pick & place
robots
YP-X

CLEAN

CONTROLLER INFORMATION

Arm type

Gantry type

Moving arm
type

Pole type

XZ type