

# SXYx 3 axes / ZS

- Moving arm type
- Whipover
- Z-axis shaft vertical type

## Ordering method

**SXYx - S** [ ] [ ] [ ] [ ] **15** [ ] **RCX240** [ ] [ ] [ ] **BB**

Model	Cable	Combination	X-axis stroke	Y-axis stroke	ZR-axis	Z-axis stroke	Cable length	Controller	Usable for CE marking	Option I/O <sup>Note 1</sup>	Network option	Battery
		M1 M3	15 to 85cm	15 to 35cm	ZS12 ZS6		3L: 3.5m (Standard) 5L: 5m 10L: 10m		No entry: Standard E: CE	N.P. Standard I/O <sup>Note 1</sup> N1, P1: 40/24 N2, P2: 64/40 N3, P3: 88/56 N4, P4: 112/72	No entry: None CC: CC-Link DN: DeviceNet PB: Profibus EN: Ethernet YC: YC-Link <sup>Note 2</sup>	BB: 4 pcs

Note 1. N to N4 if NPN was selected, or P to P4 if PNP was selected for the I/O board.  
Note 2. Available only for the master.

## Specification

	X-axis	Y-axis	Z-axis: ZS12	Z-axis: ZS6
Axis construction <sup>Note 1</sup>	F14H	F14		-
AC servo motor output (W)	200	100		60
Repeatability <sup>Note 2</sup> (mm)	+/-0.01	+/-0.01		+/-0.02
Drive system	Ball screw (Class C7)	Ball screw (Class C7)	Ball screw (Class C10)	
Ball screw lead (Deceleration ratio) (mm)	20	20	12	6
Maximum speed <sup>Note 3</sup> (mm/sec)	1200	1200	1000	500
Moving range (mm)	150 to 850	150 to 350		150
Robot cable length (m)	Standard: 3.5 Option: 5,10			

Note 1. Use caution that the flange machining (installation holes, tap holes) differs from single-axis robots.  
Note 2. Positioning repeatability in one direction.  
Note 3. The total of the X and Y strokes should be 1000mm or less.  
Note 4. When the X-axis stroke is longer than 750mm, resonance of the ball screw may occur depending on the operation conditions (critical speed). In this case, reduce the speed setting on the program by referring to the maximum speeds shown in the table below.

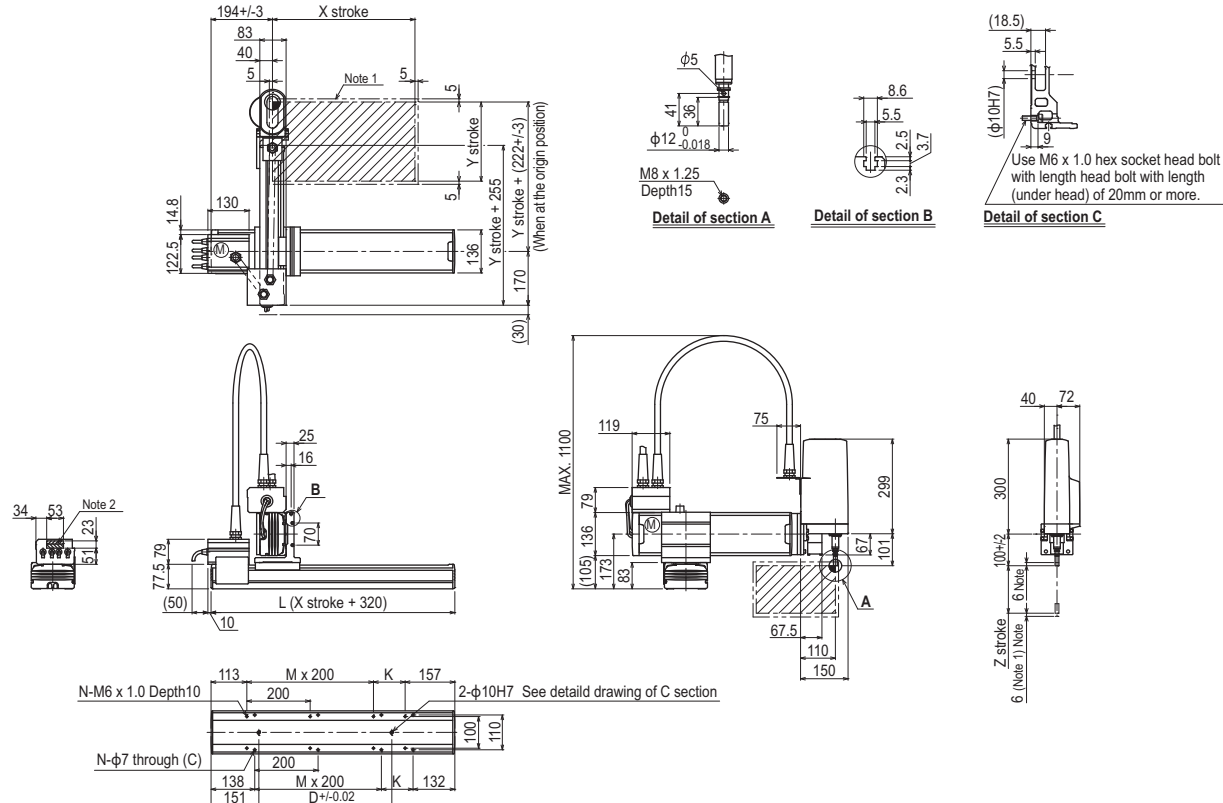
## Maximum payload (kg)

Y stroke (mm)	ZS12	ZS6
150 to 350	3	5

## Controller

Controller	Operation method
RCX240	Programming / I/O point trace / Remote command / Operation using RS-232C communication

## SXYx 3 axes / ZS M1



X stroke <sup>Note 3</sup>	150	250	350	450	550	650	750	850	
L	470	570	670	770	870	970	1070	1170	
K	200	100	200	100	200	100	200	100	
D	240	240	420	420	600	600	780	960	
M	0	1	1	2	2	3	3	4	
N	4	6	6	8	8	10	10	12	
Y stroke <sup>Note 3</sup>	150	250	350						
Z stroke	150								
Maximum speed for each stroke (mm/sec) <sup>Note 4</sup>	X-axis	1200				960	780		
	Speed setting	-				80%	65%		

Note 1. The moving range when returning to origin and the stop position when stopping by the mechanical stopper.  
Note 2. The shaded position indicates a user cable extraction port.  
Note 3. The total of the X and Y strokes should be 1000mm or less.  
Note 4. When the X-axis stroke is longer than 750mm, resonance of the ball screw may occur depending on the operation conditions (critical speed). In this case, reduce the speed setting on the program by referring to the maximum speeds shown in the table at the left.

APPLICATION  
Compact single-axis robots  
TRANSERO  
Single-axis robots  
FLIP-X  
Linear motor single-axis robots  
PHASER  
Cartesian robots  
XY-X  
SCARA robots  
YK-XG  
Pick & place robots  
YP-X  
CLEAN  
CONTROLLER INFORMATION  
Arm type  
Gantry type  
Moving arm type  
Pole type  
XZ type